



DVP SERIES PROGRAMMABLE LOGIC CONTROLLER



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DVP-PLC Series System Integration

Functionality

Ultra slim series

Superior functionality

Cost effective



**SA
SERIES**

MPU: 12 points (8DI+4DO)
Share extension module with SS series
Double larger capacity than SS series
Five times more data registers than SS series
Dual-port, abundant instructions
high-speed pulse output/input.....



**SS
SERIES**

Ultra slim series
MPU: 14 points (8DI+6DO)
Extension unit: 8 and 16 points
Complete analog input/output module
Dual communication port, abundant
instructions, high-speed pulse input/output
Cost effective



**SX
SERIES**

MPU: 10 points (4DI+2DO+2AI+2AO)
Major function spec.: same as SA series
(Built-in numerical display (correspond to internal register))
Additional 2CH analog voltage/current inputs in MPU (Bipolar/12-bit)
Additional 2CH analog voltage/current outputs in MPU (Bipolar/12-bit)



**ES
SERIES**

MPU: 14, 24, 32 and 60 points
Variety combination extension units (8, 16, 24 and 32 points)
Dual communication port, abundant instructions,
high-speed pulse input/output
Cost effective



**EX
SERIES**

MPU: 20 points (8DI+6DO+4AI+2AO)
Built-in 4CH analog inputs and 2CH analog outputs
Dual communication port, abundant instructions,
high-speed pulse input/output
Cost effective



**EH
SERIES**

MPU: 16, 20, 32, 48, 64, 80 points
Extension units: 8, 16, 32 and 48 points
Program capacity: 16K, 10000 words for data register...
CPU+ASIC (dual CPU), high-speed algorithm (up to 0.24us)
ASIC design to support high-speed pulse input (4CH, up to 200KHz)
ASIC design to support high-speed pulse output (2CH, up to 200KHz)
Abundant peripherals and instructions
Additional variety extension cards (AD, DA, COM)
Built-in convenient instructions for PLC LINK, position control,
communication control, etc.

- **Abundant instructions -- easy to program and reduce maintenance cost**
- **Delta mechanical and electrical products -- AC drive, Servo, HMI, encoder... Provide you economic/additional value solution**
- **Specific instructions -- possess communication instructions, Servo drive position instructions and variety special purpose instructions to save development cost**
- **Integrate research and application -- fast and useful technology service**
- **UL/CE marking -- excellent in quality assurance**
- **ISO9001 certification -- complete research management**

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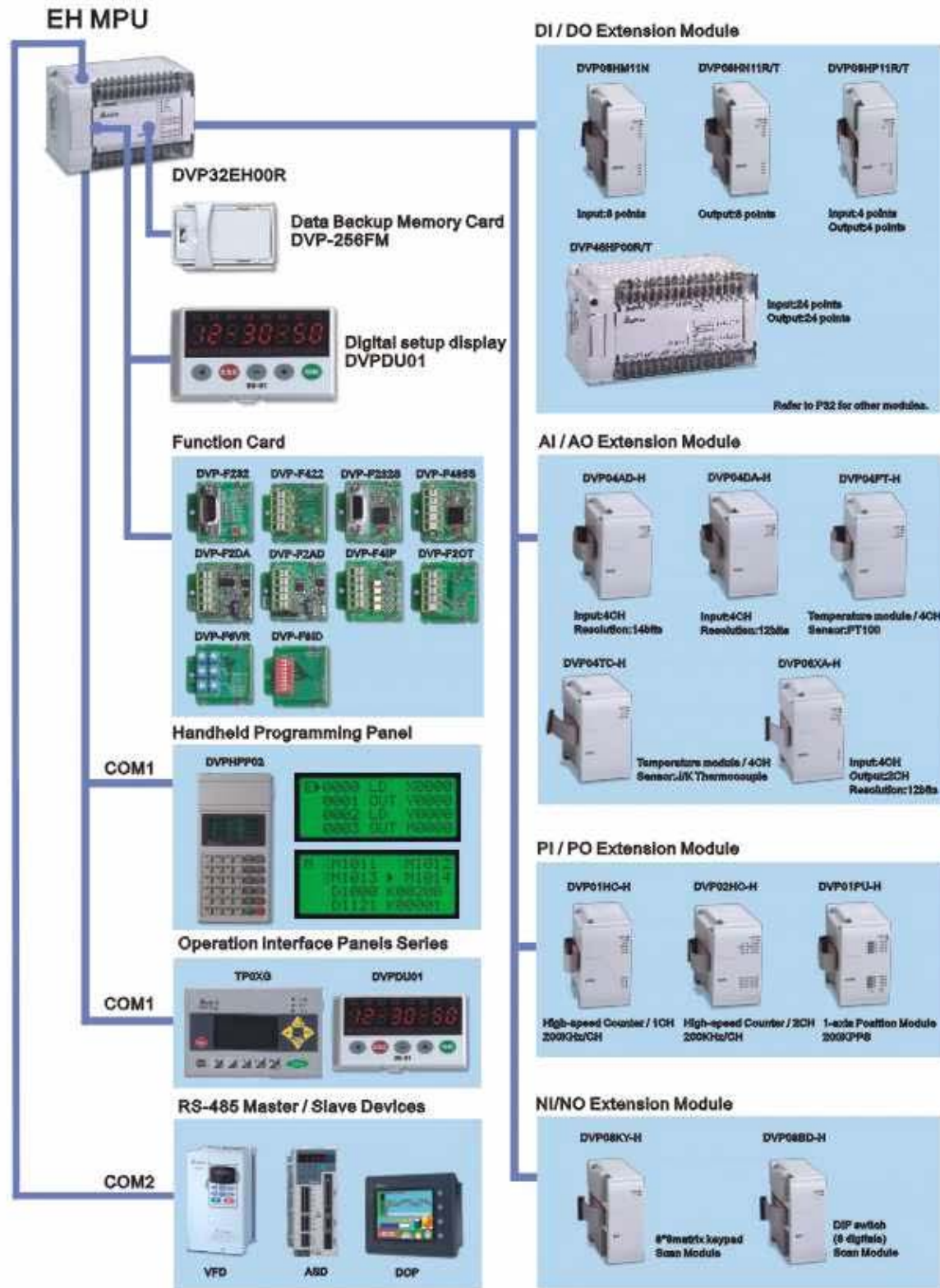
Points

Spec. Model	AC Input	DC Input	Potentiometer Input point	RUN/STOP switch	MPU built-in analog I/O point	Built-in high-speed I/O unit	File register (words)	PLC LINK	Removable terminal
ES	○	○	—	— *	—	○	—	—	— *
EX	○	○	—	—	○	○	—	—	—
SS	—	○	—	○	—	○	—	—	○
SA	—	○	○	○	—	○	1,600	○	○
SX	—	○	—	○	○	○	1,600	○	○
EH	○	—	○	○	Optional	○	10,000	○	○

* There is RUN/STOP switch and removal terminals for 60 points MPU of ES series.

Spec. Model	Built-in display screen (2 digitals with hexadecimal)	Data backup memory card	Real time clock	Memory type	Program capacity (Steps)	Digital I/O module (DI/DO)	Analog I/O module (AI/AO)	Pulse I/O module (PI/PO)	Numeric I/O module (NI/NO)
ES	—	—	—	EEPROM	4K	○	—	—	—
EX	—	—	—	EEPROM	4K	○	—	—	—
SS	—	—	—	EEPROM	4K	○	○	—	—
SA	—	—	○	SRAM+battery	8K	○	○	—	—
SX	○	—	○	SRAM+battery	8K	○	○	—	—
EH	—	Optional	○	SRAM+battery	16K	○	○	○	○

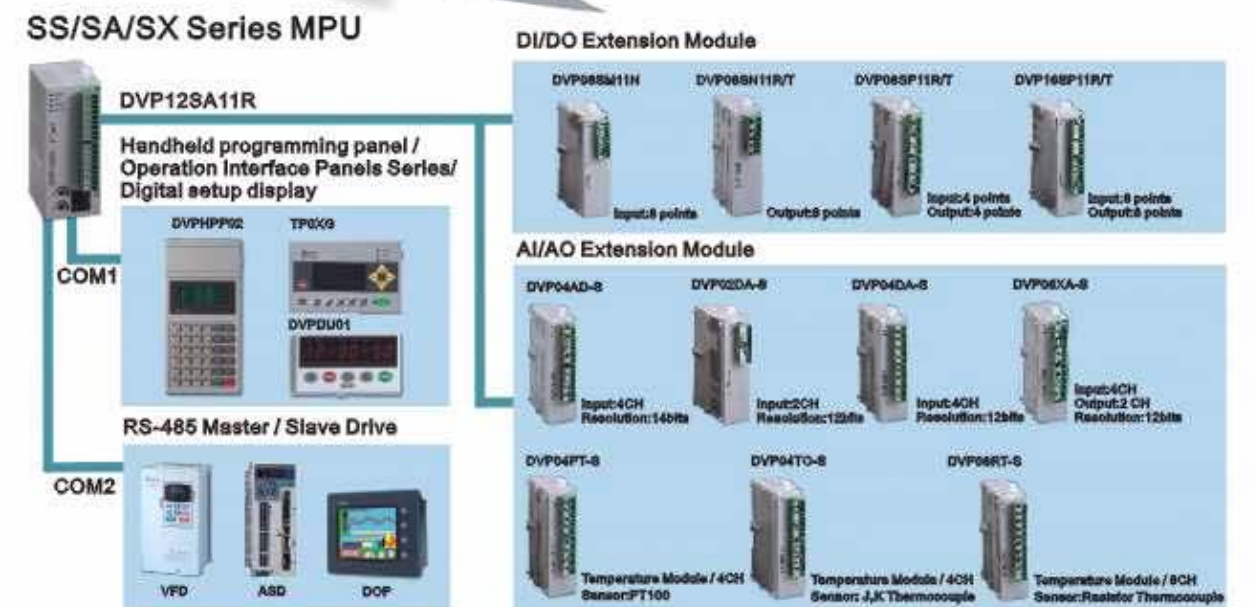
EH Series System Integration



ES/EX Series System Integration



SS/SA/SX Series System Integration



Basic • Abundant Instruction ES/EX/SS Functional Specification

High Functionality • Various Interfaces • Abundant Peripheral SA/SX/EH Functional Specifications

Item		Function	Remarks	
Control Method		Store program, cyclic scan system		
I/O Processing Method		Batch processing (when END instruction is executed), I/O refresh instruction is available		
Execution Speed		Basic instruction (several us)	Application instructions (10 ~ hundreds us)	
Program Language		Instruction + ladder diagram + SFC	Including the Step Instructions	
Program Capacity		3792 5STEPS	Built-in EEPROM	
Instructions		32 basic sequential instructions (including Step ladder instruction)	107 application instructions	
X	External input relay	X0~X177 in octal, 128 points	Total is 256 points Correspond to external input point	
Y	External output relay	Y0~Y177 in octal, 128 points		
M	Auxiliary	For general	M0~M511, M768~M999, 744 points	Total is 1280 points
		For latched	M512~M767, 256 points	
		For special	M1000~M1279, 280 points (some are latched)	
S	Step point	Initial step point (for latched)	S0~S9, 10 points	Total is 128 points Usage device of step ladder diagram (SFC)
		Zero point return (for latched)	S10~S19, 10 points (use with IST instruction)	
		latched	S20~S127, 108 points	
T	Timer	100ms timer	T0~T63, 64 points	Total is 128 points When the timer indicated by TMR instruction attains the setting, the T contact with the same number will be ON.
		10ms timer (M1028=On)	T64~T126, 63 points (when M1028=On, it is 10ms, M1028=Off, it is 100ms)	
		1ms timer	T127, 1 point	
C	Counter	16-bit count up for general	C0~C111, 112 points	Total is 128 points When the counter indicated by CNT (DCNT) instruction attains the setting, the C contact with the same number will be ON.
		16-bit count up (for latched)	C112~C127, 16 points	
		32-bit count up/down high-speed counter (for latched)	C235~C238, C241, C242, C244, 7 points	
		1-phase 1 input 1-phase 2 inputs 2-phase 2 inputs	C246, C247, C248, 3 points C251, C252, C254, 3 points	
D	Data register	For general	D0~D407, 408 points	Total is 600 points Total is 312 points It can be memory area for storing data. E and F can be used as index indication
		For latched	D408~D599, 192 points	
		For special	D1000~D1311, 312 points	
		For index indication	E(=D1028) ~ F(=D1029), 2 points	
N	For master control nested loop	N0~N7, 8 points	Control point of master control nested loop	
P	For CJ, CALL instructions	P0~P63, 64 points	The location point of CJ, CALL	
I	Interrupt	External interrupt	I001 ~ I101 ~ I201 ~ I301, 4 points	The location pointer of interrupt subroutine
		Time interrupt	I600, 1 point (□□=10~99, time base =1ms)	
		Communication interrupt	I150, 1 point	
K	Decimal number system	K-32,768 ~ K32,767 (16-bit operation) K-2,147,483,648 ~ K2,147,483,647 (32-bit operation)		
H	Hexadecimal number system	H0000 ~ HFFFF (16-bit operation) ; H00000000 ~ HFFFFFFF (32-bit operation)		
Serial Communication port (program read/write)		COM1 : RS-232, COM2 : RS-485 (can be master or slave), COM1 and COM2 can be used simultaneously		
DI/DO, AI/AO Extension Module		ES/EX series have DI/DO extension unit (8~32 points) SS series has complete DI/DO and AI/AO module (AD, DA, PT, TC, XA, RT) Note: 8 AI/AO modules (max.) and it doesn't occupy digital I/O points		

Items		SA/SX Series	EH Series	
Control Method		Stored program, cyclic scan system		
I/O Processing Method		Batch processing (when END instruction is executed)	I/O refresh instruction is available	
Execution Speed	Basic Instruction	several us	Basic instructions (0.24 us Min.)	
	Application Instructions	10~hundreds us	10 ~ hundreds us	
Program Language		Instruction, ladder diagram, SFC		
Program Capacity		7920steps (SRAM + Battery)	16872steps (SRAM + Battery)	
Instructions		32 basic sequential instructions (including the Step Instructions)	32 basic sequential instructions (including the Step Instructions)	
		168 application instruction	187 application instruction	
X	External Input Relay	X0~X177 in octal, 128 points	X0~X377 in octal, 256 points	
Y	External Output Relay	Y0~Y177 in octal, 128 points	Y0~Y377 in octal, 256 points	
M	Auxiliary Relays	General	M0~M511, 512 points	M0~M499, 500 points
		Latched	M512~M999, 488 points	M500~M999, 500 points
		Special	M2000~M4095, 2096 points	M2000~M4095, 2096 points
S	Step Points	Initial step points	S0~S9, 10 points	S0~S9, 10 points
		Zero return	S10~S19, 10 points (use with IST instruction)	S10~S19, 10 points (use with IST instruction)
		General	S20~S511, 492 points	S20~S499, 480 points
		Latched	S512~S895, 384 points	S500~S899, 400 points
		Alarm	S896~S1023, 124 points	S900~S1023, 124 points
		Timers	T0~T199, 200 points (T192~T199 is for subroutine)	T0~T199, 200 points (T192~T199 is for subroutine)
T	Timers	100ms	T250~T255, 6-point accumulative type	T250~T255, 6-point accumulative type
		10ms	T200~T239, 40 points	T200~T239, 40 points
		1ms	T240~T245, 6-point accumulative type	T240~T245, 6-point accumulative type
			T246~T249, 4-point accumulative type	T246~T249, 4-point accumulative type
		16-bit count up	C0~C95, 96 points	C0~C99, 100 points
		32-bit count high-speed up/down	C96~C199, 104 points (latched)	C100~C199, 100 points
C	Counters		C200~C215, 16 points	C200~C219, 20 points
			C216~C234, 19 points	C220~C234, 15 points
			C235~C242, 1 phase 1 input, 8 points	C235~C244, 1 phase 1 input, 10 points
			C246~C249, 1 phase 2 inputs, 3 points	C246~C249, 1 phase 2 input, 4 points
D	Data registers		C251~C254, 2 phase 2 inputs, 3 points	C251~C254, 2 phase 2 input, 4 points
		General	D0~D199, 200 points	D0~D199, 200 points
		Latched	D200~D999, 800 points	D200~D999, 800 points
		Special	D2000~D4999, 3000 points	D2000~D9999, 8000 points
	Index register	D1000~D1999, 1000 points (some are latched)	D1000~D1999, 1000 points (some are latched)	
		E0~E3, F0~F3, 8 points	E0~E7, F0~F7, 16 points	

Item		SA/SX Series	EH Series
File registers (extension register for saving data)		0-1599 (1600 points)	0-9999 (10000 points)
N	For master control nested loop	N0-N7, 8 points (control point of master control loop)	
P	For CJ, CALL instructions	(location pointer of CJ and CALL)	
I	Interrupt	External Interrupt	I000(X0), I100(X1), I200(X2), I300(X3), I400(X4), I500(X5); 6 points (all are rising-edge trigger)
		Time interrupt	I600(1ms), I700(1ms) (□□=1~99)
		High-speed counter	I010, I020, I030, I040, I050, I060; 6 points
		Pulse interrupt	I110, I120, I130, I140; 4 points
		Communication	I150, 1 point
K	Decimal	K-32,768 ~ K32,767 (16-bit operation)	
		K-2,147,483,648 ~ K2,147,483,647 (32-bit operation)	
H	Hexadecimal	H0000 ~ HFFFF (16-bit operation), H00000000 ~ HFFFFFFF (32-bit operation)	
Serial Communication (program read/write)		COM1: RS-232, COM2: RS-485(Master/Slave), COM1 and COM2 can be used simultaneously	
Potentiometer		MPU is built in 2 points (with instruction to read settings)	
RTC		MPU is built in RTC (Real time clock)(with instruction to read time and time reached comparison instruction)	
High-speed pulse output (for EH series)		Max. output frequency is 200KHz (DVP20EH00T/DVP32EH00T)	
Extension Card (for EH series)		RS-232 card, RS-422 card, Potentiometer/ DIP Switch card, Transistor Output (2OT)Card, 2AD Card, 2DA Card, COM3 card (RS-485), COM3 card (RS-232), digital input card (4 IP)	
Program Memory Card (for EH series)		Allow to backup PLC program and data or copy PLC; Program can be burned via HPP02 or WPLSoft	
Special Extension Module		Share modules AD, DA, PT, TC, XA, RT with SS series (Max. 8 Extension Units, not occupy digital I/O points)	AD, DA, PT, TC, XA, HC, PU (Max. 8 Extension Units, not occupy digital I/O points)

DVP Series PLC Special Function/ Specification Comparison

Spec. Model	Latched data register (Words)	Data backup memory card	MPU built-in analog I/O	High-speed pulse I/O	
				High-speed counter (PI unit)	Pulse generator(PO Unit)
ES	192	-	-	single phase (2 sets-X0/X1, 30KHz Max.)	2 CH (10KHz Max.) Acceleration/ deceleration control
EX	192	-	4 CH IN(resolution: 10-bit, bipolar input) 2 CH OUT(resolution: 8-bit, unipolar output)	single phase (2 sets-X2/X3, 10KHz Max.) AB phase (1 set, 7KHz Max.) Total bandwidth of PI/PO is 30KHz.	2 CH (10KHz Max.) Acceleration/ deceleration control
SS	192	-	-	single phase (2 sets-X0/X1, 30KHz Max.)	1 CH (50KHz Max.) smooth acceleration/ deceleration control
SA	3800	-	-	single phase (4 sets-X2-X5, 10KHz Max.) AB phase (1 set, 7KHz Max.) Total bandwidth of PI/PO is 30KHz.	2 CH (200KHz Max.) smooth acceleration/ deceleration control position instruction
SX	3800	-	2 CH IN(resolution: 12-bit, bipolar input) 2 CH OUT(resolution: 12-bit, bipolar output)	Low-speed: single phase (6 sets, 20KHz Max.) High-speed: single phase (4 sets, 200KHz max.) AB phase (4 sets, 100KHz max.)	2 CH (200KHz Max.) smooth acceleration/ deceleration control position instruction
EH	8800	copy PLC rapidly (Optional)	optional (use either 2 CH IN or 2 CH OUT at one time) 2 CH IN (resolution: 12-bit, unipolar input) 2 CH OUT (resolution: 12-bit, unipolar output)	Low-speed: single phase (6 sets, 20KHz Max.) High-speed: single phase (4 sets, 200KHz max.) AB phase (4 sets, 100KHz max.)	2 CH (200KHz Max.) smooth acceleration/ deceleration control position instruction

ASIC Design Structure High-speed Calculation

EH series

- Adopt dual processors with CPU+ASIC and distribution calculation
- Speed of basic instructions is up to 0.24us
- High-speed pulse output is up to 200KHz and built-in smooth acceleration/deceleration control
- High-speed counter frequency could reach 200KHz per set and total is four sets.
- I/O module refresh interface, not occupy program scan time
- Built-in multi-group external interrupt function



Extension cards for EH Series

When designing system by PLC, following condition may occur. To avoid buying whole module for an analog output, following extension cards are provided for EH series.

Usage timing and application requirement	Solution (correspond to extension card model no.)	Installation
When system specification is modified, you don't have enough points for use and you need only 1-4 input points.	DVP-F4IP	Example: DVP-F232
Output point of MPU is relay and you need 1-2 points more with transistor type.	DVP-F2OT	
You need 1-2 analog output points to control AC drive speed.	DVP-F2DA	
There is space limit for installing and need to deal with analog signal.	DVP-F2AD	
You need to connect PLC to PC and HMI and also control AC drive.	DVP-F232S	
You need to connect PLC to PC and HMI and also control AC drive.	DVP-F485S	
When parameters are needed to set by DIP switch without occupying any input points.	DVP-F8ID	
When built-in COM2 is RS-485, but what you need is RS-232. You want to use MODEM to remote control PLC	DVP-F232	
When built-in COM2 is RS-485, but what you need is RS-422.	DVP-F422	
If there are 3-8 variables needed to modify by requirement very often.	DVP-F6VR	

PLC Program Copy Card

- EH series (MPU with 32 points and more) with data backup memory card (optional)
- Data backup for portability
 - Faster speed to download numerous PLCs (copy PLC)
 - Larger capacity to save variety data
 - Password protection



Force ON / OFF setting by MPU input point X

SA/SX/EH series MPU provides input points to force On/Off setting. When user tests program by WPLSoft in office or factory, user can simulate the action of input point X to meet application requirement without connecting the input point circuit or switch.

Built-in Two Serial Communication Ports

DVP-PLC is built in two serial communication ports. It can connect to PC and HMI simultaneously and also have variety communication instructions to simplify traditional programming process. Following is functional specification for each serial communication port.

PLC Type	ES/EX/SS		SA/SX		EH	
COM 1	Communication Port	RS-232		RS-232		RS-232
	Working Mode	Slave		Slave		Slave
	Protocol	Modbus ASCII mode		Modbus ASCII / RTU mode		Modbus ASCII / RTU mode
	Baud Rate (bps)	9600		9600, Max. is up to 115200		9600, Max. is up to 115200
	Monitor	PC / HMI		PC / HMI		PC / HMI
COM 2	Communication Port	RS-485		RS-485		RS-485/It can be changed to RS-232 or RS-422
	Working Mode	Master	Slave	Master	Slave	Master
	Protocol	Modbus Instructions (user-defined format) Modbus	Same as COM1	Modbus Instructions (user-defined format)	Same as COM1	Modbus Instructions (user-defined format)
	Baud Rate(bps)	9600 / 19200 / 38400	9600	9600, Max. is up to 115200	9600, Max. is up to 115200	9600, Max. is up to 115200
	Connection Device	PLC/AC drive...	Same as COM1	PLC/AC drive...	Same as COM1	PLC/AC drive/MODEM...
	Monitor	N/A		N/A		PC / HMI
COM 3	Communication Port	N/A		N/A		RS-485, RS-232
	Working Mode	N/A		N/A		Slave / Modbus
	Protocol	N/A		N/A		9600 / 19200 / 38400
	Monitor	N/A		N/A		PC / HMI

Supports Modbus Serial Instructions (For all series)

DVP-PLC is not only built in RS-485 serial communication port but also provides variety instructions of Modbus serial communication with two modes (ASCII mode and RTU mode). User only needs to fill device's ID, parameter's address and data for read/write into instruction without understanding communication protocol or writing complicated checksum program. Besides, it also provides many state flags, including communication time-out, transmission data error and transmitted data is receiving. Each state in communication is in your hand and makes you finish communication programming easily.



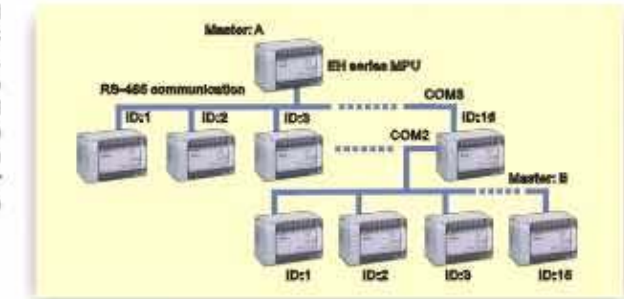
PLC Easy Link (1:N) Function (For EH/SA/SX series)

DVP-PLC provides EASY LINK function. At the right figure, you only need to write parameters address and length into special register without programming. Master will auto exchange data between devices (16 words for read/write). 16 slave devices max. (not only for DVP-PLC, but also DELTA other mechanical and electrical products that has serial communication and only support Modbus protocol, such as AC drive, temperature, Servo, etc.)



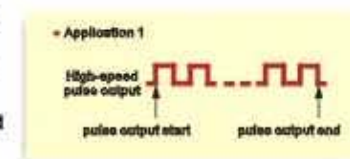
PLC Easy Link (N : N) Function (For EH series)

Using PLC Link function, max. N for single level (1: N) is 16 devices. If you need more than 16 devices, you need to use multi-level (N:N) network. You need to choose one device in first level to be master (such as Master B at the right figure), and then insert COM3 extension card (DVP-F485S) into it to connect to the first level and using built-in COM2 (RS-485) to connect to the new level. Master A and Master B control data exchange in whole network.

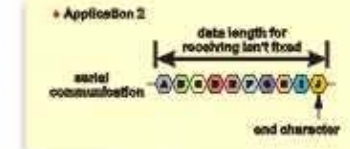


Variety Interrupt Source Requirement

1. External interrupt could reach 6 points
2. Timer interrupt
3. High-speed counter reached interrupt
4. Pulse output start or finish interrupt
5. Specific communication receiving word interrupt



There is correspondent interrupt number to execute relative action without effecting by scan time when high-speed pulse output start or end.



In serial communication application, received data length is the signal to distinguish if it finishes receiving data or not. When the received length is not fixed, you can use specific character to be the end character and produce correspondent interrupt number to execute relative action.

When received data length is not fixed, using specific character to show completed receive.

Embedded Digital Setting Display DVPDU01



- DU-01 can be inserted into extension slot of EH series (32 points or more MPU). You can set start-up display, monitor specific device and power saving mode function. PLC internal devices, including real time clock, bit device (X, Y, M, S), word device (T, C, D) and internal CR in extension module, could read display or write settings.
- It could read/write to PLC internal program P, data register D and file register F. It also could be used to copy or transmit program data and support PLC password protection. DU-01 can be used for all DVP series.

SX MPU Built-in A/D, D/A and 2-digital 7-segment Display Module

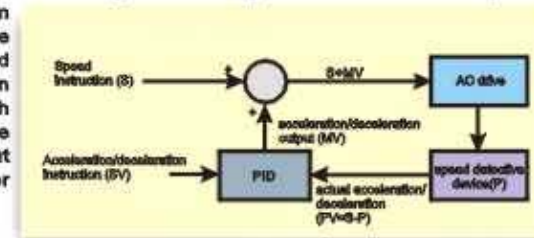


- SX MPU is built in 2CH A/D and 2CH D/A with 12-bit resolution and bi-polar input/output. It provides economic solution and read/write special D to get digital value of A/D conversion and specific analog voltage output without using FROM/TO instructions.
- Built-in 2 digitals 7-segment display and its content corresponds to special D for user display anything, such as error code or ID when using PLC Link function for network. System maintenance is fast and easy.

PID Control Instructions

DVP-PLC provides PID control instruction for automatic control speed or automatic control temperature application and it can be used repeat in program. Take the right figure for example, the algorithm method is: read actual speed parameter and acceleration/deceleration speed instruction (SV) from analog input (AI) and do PID calculate with user-defined P, I and D to get suitable output control value MV. To combine MV and speed instruction S to control output frequency of AC drive by analog output (AO) to make motor speed in the setting range of user expectation.

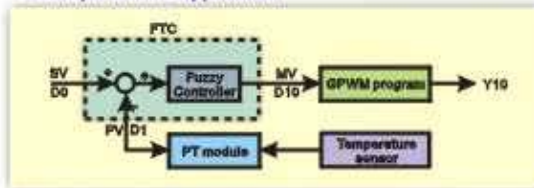
• Block diagram when using PID instruction to control speed



Fuzzy Temperature Control (For EH/SA/SX series)

User only needs to set (target value D0 (SV)) and present value D1 (PV)) to get an output instruction D10 (MV) after calculating by fuzzy logic algorithm to be the parameter for GPWM program to do On/Off control to Y10. No need to set other control parameters.

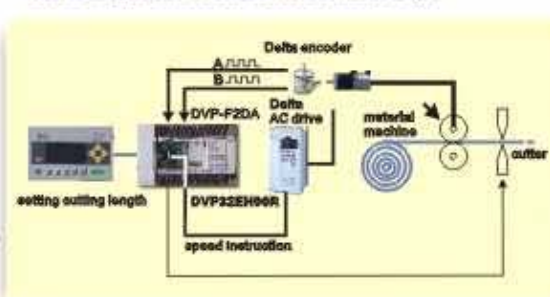
• Example for FTC application



High-speed Counter

- There are 4~6 points high-speed counter for all DVP-PLC series. And the features are:
1. Settings for counter value reached could be up to 4-8 sets
 2. Could set interrupt number when counter value reached settings
 3. Could set contact Y number to active immediately (ON/OFF) by counter value reached setting
 4. Could set high-speed counter number to clear immediately by counter value reached setting
 5. Possess counting mode of double frequency (1-4 times)
- Possess external input to control start or stop

• The Cutting Machine control with variable length



Spec.	1 phase 1 Input		1 phase 2 Inputs		2 phase 2 Inputs	
	Points	Bandwidth	Points	Bandwidth	Points	Bandwidth
ES/EX/SS	4	30KHz	1	30KHz	1	7KHz
SA/SX	6	30KHz	1	30KHz	1	7KHz

Note: Bandwidth means total of input and output frequency. When counting 1 point by 1 phase 1 Input high-speed counter, max. count frequency could be up to 30KHz.

Spec.	General		Hardware high-speed counter					
	1 phase 1 Input		1 phase 1 Input		1 phase 2 Input		2 phase 2 Input	
	Points	Bandwidth	Points	Count frequency	Points	Count frequency	Points	Count frequency
EH	6	20KHz	4(2/2)	200KHz/30KHz	4(2/2)	200KHz/30KHz	4(2/2)	200KHz/30KHz

Note: There are four groups of hardware high-speed counters for EH series. The count frequency of two points could reach 200 KHz per point and 30 KHz for the other two points.

Pulse Output

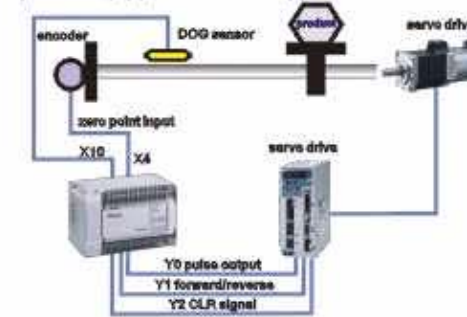
There is 2-point high-speed pulse output for each DVP-PLC series. For EH series, each output channel could output 200KHz pulses individually and provides acceleration/deceleration control instruction to finish multi-segment, smooth and precision position control easily. It could control closed circuit by using with built-in hardware high-speed counters to compensate drive's components aging or other components' error to get long time steady control. Refer to following table for pulse output comparison of each series:

Spec.	Output points	Max. output frequency		Function Features
		Y Output	Y0 Y1 (Y2)	
ES/EX/SS	2	Y0, Y1	10KHz 10KHz	Possess acceleration / deceleration control
SA/SX	2	Y0, Y1	50KHz 10KHz	Possess smooth acceleration / deceleration control
EH	2	Y0, Y2	200KHz 200KHz	Possess smooth acceleration / deceleration control



Position Control Instruction (For EH series)

• Example for simply position control application



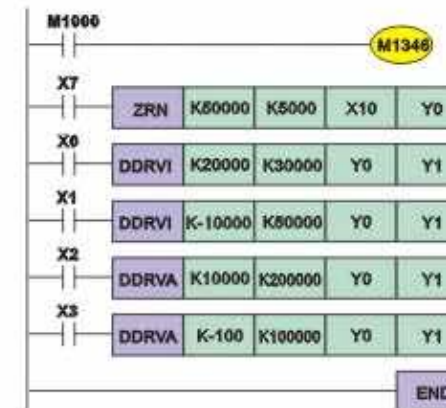
For EH series, there are following simply position instruction, including zero return, acceleration / deceleration pulse output and position control instruction of relative/absolute position.

API	Instruction		Function
	16-bit	32-bit	
155	ABSR	DABSR	Read ABS current value
156	ZRN	DZRN	Zero return
157	PLSV	DPLSV	Pulse output
158	DRVI	DDRVI	Relative position
159	DRVA	DDRVA	Absolute position

Explanation:

- ♦ When X7=On, the action of zero return will start and it will start to output pulse from Y0 with 50KHz frequency. When reaching DOG input (X10=On), it will output pulse from Y0 by JOG with 5KHz frequency and stop when X10=Off. When M1348=On (clear signal flag), the action of zero return will end and output Y2 clear signal to servo drive.
- ♦ When X0=On, it will output 20,000 pulses (relative position) from Y0 with 30KHz. Y1=On means forward.
- ♦ When X1=On, it will output -20,000 pulses (relative position) from Y0 with 50 KHz. Y1=Off means reverse.
- ♦ When X2=On, it will output 10,000 pulses (absolute position) from Y0 with 200 KHz. Y1=On means forward.
- ♦ When X3=On, it will output -100 pulses (absolute position) from Y0 with 100 KHz. Y1=Off means reverse.

DOG input: X10, zero return start: X7
 Relative position (+) start: X0, Relative position (-) start: X1
 Absolute position (+) start: X2, Absolute position (-) start: X3
 Y0: pulse output, Y1: forward/reverse, Y2: clear signal



Communication Control Function Additional Special Function (For EH series)

Analog Voltage/Current I/O Additional Devices (For EH series)

Extension Card for RS-232/RS-422 Communication



DVP-F232

DVP-F422

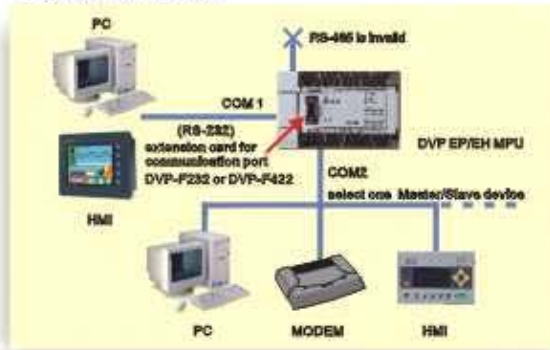
MPU is built in COM1 (RS-232) and COM2 (RS-485). When user needs to connect to peripheral, such as PC or MODEM, by using COM2 to be RS-232 or RS-422, he could use this extension card. Besides communication interface, its communication function is the same as original COM2 and it can use to be Slave mode or Master mode.

Caution: After inserting this card, original built-in COM2 (RS-485) will be invalid and PLC will set COM2 to be occupied by RS-232 card.

Specifications

Item	Explanation	
Model no.	DVP-F232	DVP-F422
COM port	Standard RS-232C	Standard RS-422
Insulation method	Non-insulation	
Transmission distance	15m	500m
Consumption method	30mA/DC5V (supply from PLC MPU)	
Communication protocol	Mode	
	Master/Slave, half-duplex, bidirection data transmission/receive	
	Speed rate	110/160/300...9600/19200/38400/87600/115200
	Data bits	7 or 8
	Stop bits	1 or 2
Parity check	None, Even, Odd	
Communication indication	TX (transmission data), RX (receive data)	
Connection device	Possess RS-232C interface	Possess RS-422 interface

System Connection



Additional RS-232 / RS-485 port



DVP-F485S

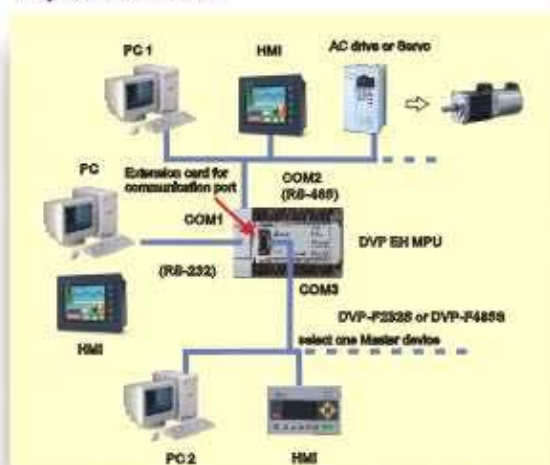
DVP-F232S

When two built-in COM1 (RS-232) and COM2 (RS-485) are not enough for use, you can add one COM by this card (number is 3 and called COM3). There are two interfaces, RS-232 and RS-485, for you to use. Its general function is the same as COM1 but communication baud rate is 9600/19200/38400 bps. Usage limit: PC1 and PC2 can't execute ladder diagram monitor function simultaneously when COM2 is slave mode and connect to PC1 with executing WPLSoft and COM3 also connects to PC2 with executing WPLSoft. But other communication function is normal. COM1 is out of this limit.

Specifications

Item	Explanation	
Model no.	DVP-F232S	DVP-F485S
Com port	Standard RS-232C	Standard RS-485
Insulation method	Non-insulation	
Transmission distance	15m	500m
Consumption method	30mA/DC5V (supply from PLC MPU)	
Communication protocol	Mode	
	Slave, half-duplex, bidirection data transmission/receive	
	Speed rate	9600/19200/38400
	Data bits	7
	Stop bits	1
Parity check	Even	
Communication indication	TX (transmission data), RX (receive data)	
Connection device	Possess RS-232C interface	Possess RS-485 interface

System Connection



Additional analog voltage/current input device



DVP-F2AD

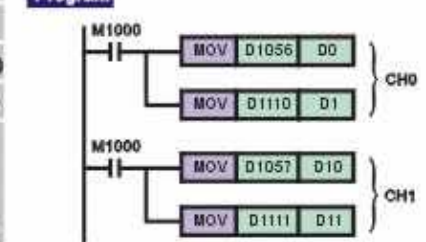
User can get A/D conversion value saved in special D by reading special D that corresponds to current value or average value.

There are 2 analog input points supported by F2AD card and their characteristics are shown in the following:

Item	Voltage output	Current output
Analog signal	DC 0~+10V	DC 0~20mA
Resolution (12bits)	2.6mV (10/4000)	10uA (20/2000)
Input impedance	40KΩ	250Ω
Refresh time for conversion	D1118 setting (≥K5, unit: ms)	
Digital input	Current value	D1056(CH0) D1057(CH1)
	Average value	D1110(CH0) D1111(CH1)
Characteristic curve		



Program



◆ Conversion calculation of CH0 AD :
Detector (voltage) produces an input voltage CH0.
If the value D1 reads is K1472, it means input voltage is

$$= 1472 \times \frac{10V}{4000} = 3.68V$$

◆ Conversion calculation of CH1 AD :
Detector (current) produces an input current CH1.
If the value D11 reads is K1234, it means input current is

$$= 1234 \times \frac{20mA}{2000} = 12.34mA$$

Additional analog voltage/current output device

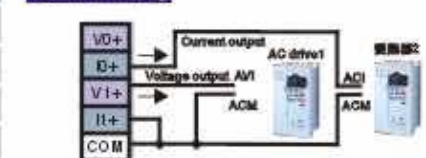


DVP-F2DA

User can move value to D1116(CH0) or D1117(CH1) to get correspondent output voltage by using instruction MOV. Please connect IO+ or I1+ to COM to have a short circuit when circuit output is unused.

Item	Voltage output	Current output
Analog signal	DC 0~+10V	DC 0~20mA
Output impedance	0.6Ω and less	0.6Ω and less
Resolution (12bits)	2.6mV (10/4000)	5uA (20/4000)
Refresh time	D1116 setting (≥K5, unit: ms)	
Digital input	D1116 (CH0)	D1117 (CH1)
Characteristic curve		

Terminal Wiring



Program



◆ Conversion calculation of CH0 DA :
The current is outputted to ACI of AC drive to be speed control. If you need current 12.34mA, you should give D0:

$$= 12.34mA \times \frac{4000}{20mA} = 2468$$

◆ Conversion calculation of CH1 DA :
The voltage is outputted to AVI of AC drive to be speed control. If you need voltage 5.23V, you should give D1:

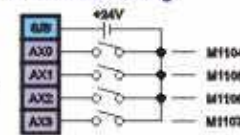
$$= 5.23V \times \frac{4000}{10V} = 2092$$

Digital input (4 points)



DVP-F4IP card provides 4 digital Input points with photocoupler isolation between PLC. After system finishes scan every time, it will read 4 bits of these 4 digital Input points automatically and set the states separately in M1104~M1107. User can operate this four special M in the program directly.

Terminal wiring

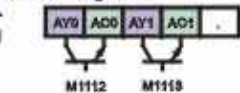


Digital output (2 points)



There are 2 digital output points that provided by DVP-F2OT card. Output type is transistor and user can drive output points by using M1112 and M1113.

I/O Diagram

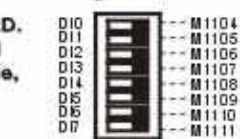


DIP switch



This digital DIP switch card (DVP-F8ID) provides 8 On/Off Input signals (DI0~DI7) to read value by using instruction API 109 SWRD. It is general used to be input interface of external data setting and doesn't occupy input point X. After system finishes every scan time, it will auto to read 8 bits of digital switch and set each state in special auxiliary relay M1104~M1111.

I/O Diagram



Potentiometer



DVP-F8VR card provides extension potentiometer VR2~VR7. Refer to API85 VRRD and API86 VRSC in application manual (programming) for detail. There are two built-in potentiometers VR0 and VR1 in EH MPU.

Data Backup Memory Card



DVP-256FM is a data backup memory card. There is a switch on it and PLC will check the state of this switch when PLC is power on. If this switch is Off, memory card will be invalid. And it is invalid to change the switch when PLC is power on. All memory data read/write action will be valid when switch is On.

Digital Setup Display (The switch for mode selection (TS-01 and TC-01) is at the back of the DU01.)



DVPDU01

TS-01 :

- ◆ Read/Write of both internal devices of PLC (eg. real time clock, bit devices (X, Y, M, S) and word devices (T, C, D)) and the Control Register (CR) inside of the extension units.
- ◆ Support the read/write of 32-bit data register.
- ◆ Set Start-up display and power save mode.
- ◆ Monitor the devices.
- ◆ If connected with accessory cable to ES-series without real time clock, the Time Display will start from 00-00-00 calculated by the microprocessor of DU01 (timing error may occur).

TC-01 :

- ◆ Read/write the program P, data register D and file register F from PLC.
- ◆ Copy program and data.
- ◆ Support the password protection of the PLC.

Analog Input Module -- DVP04AD-S (For SS/SA/SX Series)



Item	Voltage input	Current input
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog input channel	4 channels / each module	
Analog input range	±10V	±20 mA
Digital conversion range	±8000	±4000
Resolution	14 bits (1 _{LSB} =1.25 mV)	13 bits (1 _{LSB} =5 μA)
Input impedance	200 KΩ and above	250Ω
Overall accuracy	0.5% of full scale of 25°C(77°F), 1% of full scale during 0~65°C (32~131°F).	
Response time	3 ms × channels	
Isolation method	Isolation between digital and analog circuitry. There is no isolation between channels.	
Absolute input range	±15 V	±32 mA
Digital data format	2's complementary of 16-bit, 13 significant bits, support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connect to DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Analog Output Module--DVP04DA-S and DVP02DA-S(For SS/SA/SX Series)



Item	Voltage Input	Current Input
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog output channel	4 channels / each module, 2 channels / each module	
Analog output range	0~10V	0~20 mA
Digital data range	0~4000	0~4000
Resolution	12 bits (1 _{LSB} =2.5 mV)	12 bits (1 _{LSB} =5 μA)
Output impedance	0.6Ω or less	
Overall accuracy	0.8% of full scale of 25°C(77°F), 1% of full scale during 0~65°C (32~131°F).	
Response time	3 ms × channels	
Output current	20 mA max.	—
Tolerance carried impedance	1KΩ~2MΩ	0~500Ω
Digital data format	2's complementary of 16-bit, 12 significant bits	
Isolation method	There is photocoupler isolation between internal circuit and analog output and no isolation among analog channels.	
Protection	Voltage output has short circuit protection but short circuit for a long time may cause inner wiring damage and current output break.	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connect to DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Temperature Module (PT100) DVP04PT-S (For SS/SA/SX Series)




Item	Centigrade (°C)	Fahrenheit (°F)
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog input channel	4 channels per module	
Sensors type	3-WIRE PT100Ω 3850 PPM/°C(DIN 43760 JIS C1604-1989)	
Temperature input range	-200°C~600°C	-328°F~1112°F
Digital conversion range	K-2000~K6000	K-3280~K11120
Resolution	14 bits (0.1°C)	14 bits (0.18°F)
Overall accuracy	0.5% of full scale of 25°C(77°F), 1% of full scale during 0~65°C (32~131°F)	
Response time	200 ms × channels	
Isolation Method	Isolation between digital and analog circuitry. There is no isolation between channels.	
Digital data format	2's complementary of 16-bit, 13 significant bits, support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Specifications


SS/SA/SX Special Modules

Mixed Input/output Module -- DVP06XA-S (For SS/SA/SX series)




Item	Analog Input (A/D)		Analog Output (D/A)	
	Voltage	Current	Voltage	Current
Power Supply Voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)			
Analog Input/output channels	4 channels		2 channels	
Analog Input/Output range	±10V	±20 mA	0~10V	0~20 mA
Digital conversion range	±2000	±1000	0~4000	0~4000
Resolution	12 bits, 1 _{LSB} =5 mV	11 bits, 1 _{LSB} =20μA	12bits, 1 _{LSB} =2.5mV	12 bits, 1 _{LSB} =5 μA
Input Impedance (A/D), output impedance (D/A)	200 KΩ and above	250Ω	0.6Ω or less	
Overall accuracy	0.5% of full scale of 25°C(77°F); 1% of full scale during 0~55°C (32~131°F)			
Response time	3 ms × channels			
Isolation method	No Isolation			
Absolute Input range	±15 V	±32 mA	-	
Digital data format	2's complement of 16-bit, 12 significant bits; support average function (average times: K1~K4096)			
Output current	-		20 mA max.	-
Self diagnostic function	Upper bound and lower bound detection per channel		-	
Tolerance carried impedance	-		1KΩ~2MΩ	0~500Ω
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.			
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.			

Temperature Module (Thermocouple) DVP04TC-S (For SS/SA/SX series)



Item	Centigrade (°C)	Fahrenheit (°F)
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog Input channels	4 channels per module	
Sensors type	J-type or K-type thermocouple	
Temperature Input range	J: -100°C~700°C, K: -100°C~1000°C	J: -148°F~1292°F, K: -148°F~1832°F
Digital conversion range	J: K-1000~K7000, K: K-1000~K10000	J: K-1480~K12920, K: K-1480~K18320
Resolution	14 bits(0.1°C)	14 bits(0.18°F)
Overall Accuracy	0.5% of full scale of 25°C(77°F), 1% of full scale during 0~55°C (32~131°F)	
Response Time	250 ms × channels	
Isolation method	Isolation between digital and analog circuitry. There is no isolation between channels.	
Digital data format	2's complement of 16-bit, 13 significant bits; support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Temperature Module (NTC type) DVP08RT-S (For SS/SA/SX series)




Item	Centigrade (°C)	Fahrenheit (°F)
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog Input channel	8 channels per module	
Sensors type	R25=10K: 1.B25/86=3977; effective range: -20°C~100°C(-4°F~212°F) 2.MF58-103-(B25/86-3630K); effective range: -20°C~150°C(-4°F~302°F)	
Digital conversion range	1.K-200~K1000, 2.K-200~K1500	1.K-40~K2120, 2.K-40~K3020
Resolution	12 bits(0.1°C)	12 bits(0.18°F)
Overall accuracy	0.5% of full scale of 25°C(77°F), 1% of full scale during 0~55°C (32~131°F)	
Response time	200 ms × channels	
Isolation method	No Isolation	
Digital data format	2's complement of 16-bit, 12 significant bits; support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Specifications


EH Special Modules

Analog Input Module -- DVP04AD-H




Item	Voltage Input	Current Input
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog input channel	4 channels per module	
Analog Input range	±10V	±20 mA
Digital conversion range	±8000	±4000
Resolution	14 bits(1 _{LSB} =1.25 mV)	13 bits (1 _{LSB} =5 μA)
Input Impedance	200 KΩ and above	250Ω
Overall accuracy	0.5% of full scale of 25°C(77°F); 1% of full scale during 0~55°C (32~131°F)	
Response time	3 ms × channels	
Isolation method	Isolation between digital and analog circuitry. There is no isolation between channels.	
Absolute Input range	±15 V	±32 mA
Digital data format	2's complement of 16-bit, 13 significant bits; support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Analog output module -- DVP04DA-H



Item	Voltage output	Current output
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog output channel	4 channels per module	
Analog output range	0~10V	0~20 mA
Digital data range	0~4000	0~4000
Resolution	12 bits (1 _{LSB} =2.5 mV)	12 bits (1 _{LSB} =5 μA)
Output impedance	0.5Ω or less	
Overall accuracy	0.5% of full scale of 25°C(77°F); 1% of full scale during 0~55°C (32~131°F)	
Response time	3 ms × channels	
Output current	20 mA max.	-
Tolerance carried impedance	1KΩ~2MΩ	0~500Ω
Digital data format	2's complement of 16-bit, 12 significant bits	
Isolation method	Photo-couple isolation between internal circuit and analog output. There is no isolation among analog channels.	
Protection	Voltage output has short circuit protection but short circuit for a long time may cause inner wiring damage and current output break.	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Temperature Module (PT100) DVP04PT-H



Item	Centigrade (°C)	Fahrenheit (°F)
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (15%~+20%)	
Analog Input channel	4 channels per module	
Sensors type	3-WIRE PT100Ω 3850 PPM/°C(DIN 43760 JIS C1604-1969)	
Input temperature range	-200°C~600°C	-328°F~1112°F
Digital conversion range	K-2000~K6000	K-3280~K11120
Resolution	14 bits(0.1°C)	14 bits(0.18°F)
Overall accuracy	0.5% of full scale of 25°C(77°F); 1% of full scale during 0~55°C (32~131°F)	
Response time	200 ms × channels	
Isolation method	Isolation between digital and analog circuitry. There is no isolation between channels.	
Digital data format	2's complement of 16-bit, 13 significant bits; support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Specifications

EH Special Modules

Temperature Module (Thermocouple) DVP04TC-H

Item	Centigrade (°C)	Fahrenheit (°F)
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (16%~+20%)	
Analog Input channel	4 channels per module	
Sensors type	J-type or K-type thermocouple	
Input temperature range	J: -100°C~700°C, K: -100°C~1000°C	J: -148°F~1292°F, K: -148°F~1832°F
Digital conversion range	J: K-1000~K7000, K: K-1000~K10000	J: K-1480~K12920, K: K-1480~K18320
Resolution	14 bits(0.1°C)	14 bits(0.18°F)
Overall accuracy	0.5% of full scale of 25°C(77°F); 1% of full scale during 0~55°C(32~131°F)	
Response time	280 ms x channels	
Isolation method	Isolation between digital and analog circuitry. There is no isolation between channels.	
Digital data format	2's complement of 16-bit, 13 significant bits; support average function (average times: K1~K4096)	
Self diagnostic function	Upper bound and lower bound detection per channel	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.	
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.	

Mixed Analog Input/output Module DVP06XA-H

Item	Analog Input (A/D)		Analog Output (D/A)	
	Voltage	Current	Voltage	Current
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (16%~+20%)			
Analog Input/output channels	4 channels		2 channels	
Analog Input/output range	±10V	±20 mA	0~10V	0~20 mA
Digital conversion range	±2000	±1000	0~4000	0~4000
Resolution	12 bits, 1 _{LSB} =5 mV	11 bits, 1 _{LSB} =20 uA	12bits, 1 _{LSB} =2.5 mV	12 bits, 1 _{LSB} =5 uA
Input Impedance (A/D), output Impedance (D/A)	200 KΩ and above	250Ω	0.5Ω or less	
Overall accuracy	0.5% of full scale of 25°C(77°F); 1% of full scale during 0~55°C(32~131°F)			
Response time	3 ms x channels			
Isolation method	Isolation between digital and analog circuitry.		Isolation between internal circuit and analog output circuitry.	
Absolute Input range	±16 V	±32 mA	-	
Digital data format	2's complement of 16-bit, 12 significant bits; support average function (average times: K1~K4096)			
Output current	-		20 mA max.	-
Self diagnostic function	Upper bound and lower bound detection per channel		-	
Tolerance carried impedance	-		1KΩ~2MΩ	0~500Ω
Protection	-		Voltage output has short circuit protection.	
Communication mode (RS-485)	Yes, there are ASCII/RTU modes. Baud rate is selectable.			
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.			

Single-axis Position Module -- DVP01PU-H

Item	Specifications
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (16%~+20%)
Number of controlled axes	Connects up to 8 axes
Output-pulse frequency	200KHz max.
Pulse output type	Line output (DC5V, 20 mA and less)
Control Input	Left/right bound (LSP/LSN), START/STOP, DOG input, zero point input (Pg0) Hand wheel input (A/B)
Output control	Pulse output: FP (forward pulses) and RP (reverse pulses), multi-function contacts (OUT)
Action mode	JOG/zero return/1-step operation/2-step operation/2-step operation Insert/ various speed operation
Acceleration / deceleration	Acceleration and deceleration time can be set individually
Response time	When position is set, pulse will be output in 40ms after START signal is active. Trigger for left/right bound is 4ms

Specifications

EH Special Modules

1CH High-speed Counter Module -- DVP01HC-H

Item	Specifications
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (16%~+20%)
Input signal	Level: Three inputs: +5V, +12V, 24V
	Frequency: 200KHz for 1 phase 1 input, 200KHz for 1 phase 2 inputs, 200KHz (counting mode: normal frequency, double frequency and four times frequency) for 2-phase 2 inputs
Counting range	16-bit unsigned number (0~65535). (65535 can be set by controlled register and range is 1~65535) 32-bit signed number (range: -2,147,483,648~+2,147,483,647)
Counting mode	Cyclic counting method: • 16-bit: when it is 65535, the number it counts up will be 0. When it is 0, the number it counts down will be 65535. • 32-bit: when it is +2,147,483,648, the number it counts up will be -2,147,483,648. When it is -2,147,483,648, the number it counts down will be +2,147,483,647.
Output type (comparison reaches setting)	NPN open collector output DC5~24V 0.5A 2 points (YH0 and YH1)
Additional function	External input control: Enable/Disable and Preload (set start value to count)
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.

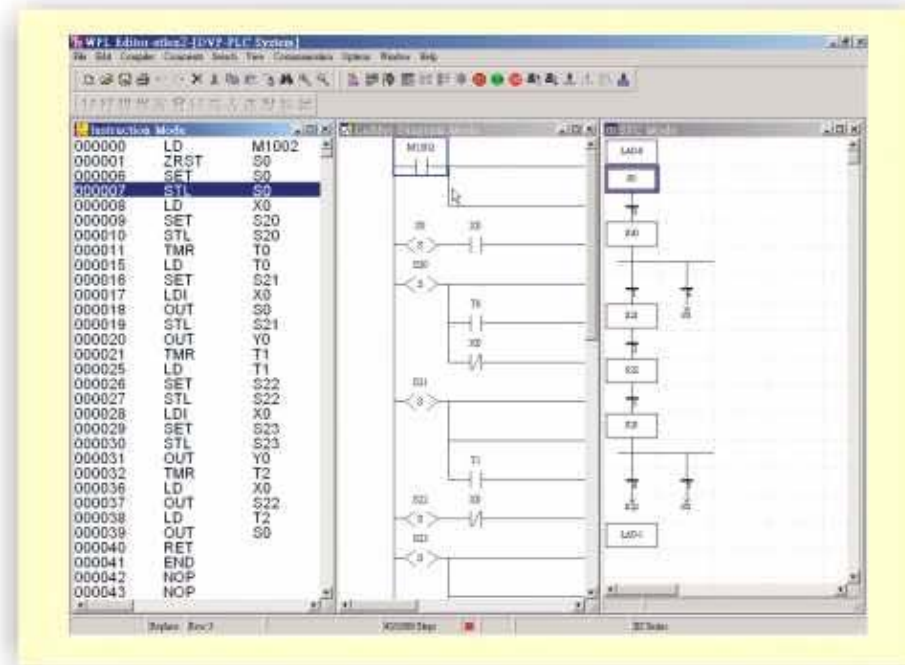
2CH High-speed Counter Module DVP01HC-H

Item	Specifications
Power supply voltage	24 VDC(20.4VDC~28.8VDC) (16%~+20%)
Input signal	Level: 24V
	Frequency: 200KHz for 1 phase 1 input, 200KHz for 1 phase 2 inputs, 200KHz (counting mode: normal frequency, double frequency and four times frequency) for 2-phase 2 inputs
Counting range	16-bit unsigned number (0~65535). (65535 can be set by controlled register and range is 1~65535) 32-bit signed number (range: -2,147,483,648~+2,147,483,647)
Counting mode	Cyclic counting method: • 16-bit: when it is 65535, the number it counts up will be 0. When it is 0, the number it counts down will be 65535. • 32-bit: when it is +2,147,483,648, the number it counts up will be -2,147,483,648. When it is -2,147,483,648, the number it counts down will be +2,147,483,647.
Output type (comparison reaches setting)	NPN open collector output DC5~24V 0.5A 2 points (YH0 and YH1)
Additional function	External input control: Enable/Disable and Preload (set start value to count)
Connection to a DVP-PLC MPU in series	When connecting to MPU, the modules are numbered from 0 to 7. 0 is the closest and 7 is the furthest to the MPU. Max is 8 modules and they do not occupy any digital I/O points.

NI/NO Module -- DVP08KY-H/DVP08BD-H

Item	DVP08KY-H	DVP08BD-H
Power supply voltage	24 VDC, supply from MPU	
External connection	Matrix keypad size could be up to 8*8	DIP switch could be up to 8 digits
Read Input value	Return key coordinate to special D	Return value to special D
Characteristics	Auto scan by ASIC in MPU and won't use much scan time and no need to write program	
Connection to a DVP-PLC MPU in series	Total of 2 modules are for these two modules to connect and it won't waste digital I/O points.	

DVP-PLC Programming Software Tool



Features

1.Windows based software : It is easy to learn and use. You could use all functions with the help file provided by WPLsoft.

2.Complete comments : Including device comment, segment comment and row comment, to have great convenience to read ladder diagram program. Besides, device comment could be copied to Excel data for use. At the same time, you could also copy Excel data to comment area for programming easily.

3.Project concept : use hierarchical method to display PLC internal system information (including system parameters, connected peripheral, program area and settings) visually to make all PLC information clearly. It is a great convenience to program development and maintenance.

4.Communication response time setting : for user to set time-out and Retry times to monitor without disconnection by interference of working environment. It also could detect communication baud rate of scan time for auto connection rapidly.



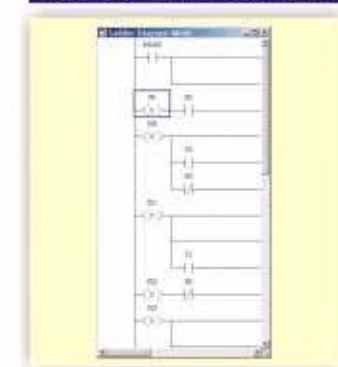
5.Real time clock setting : for user-defined time or computer time setting.



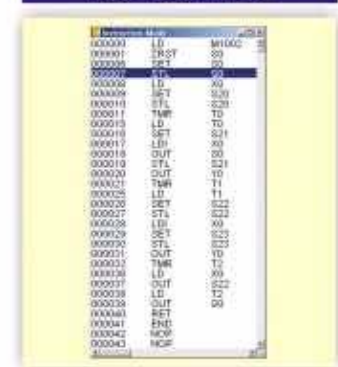
6.Variety connections : It provides two connection methods : direct connection and Modem connection. The common use-direct connection provides different baud rate setting and could up to 115200 bps to shorten program upload / download time. It also provides real-time monitor function and on-line programming function to execute on-line update instruction immediately after compiling without stopping PLC/ downloading program/ running PLC again to shorten program development time and modified time.

7.Three program languages for input : Instruction (IL), ladder diagram (LAD) and sequential function chart (SFC). These three languages could convert to one another. Editor Interface is the same as general editor and easy to learn and use. It could also input and save without successful compiler at any time.

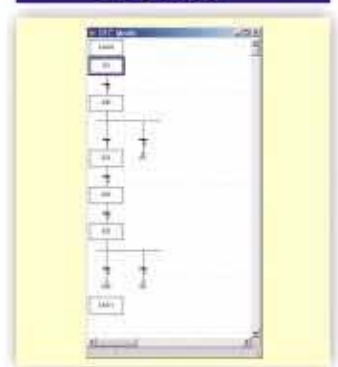
Ladder diagram editor mode



Instruction mode



SFC mode



8.Built-in variety PLC device editors : Including devices M, S, T, C, D and file register. The content of device can be saved or downloaded to PLC or upload to provide great convenience for program development or maintenance.

9.On-line auxiliary function :

- ◆ **RS - 485 Protocol Setting** - you should set communication protocol control register D1120 before setting serial communication. Using this software, you can get the correspondent value that should set in D1120 easily.
- ◆ **LRC/CRCGenerator** - When designing Modbus serial communication, master must calculate checksum value of serial data. At development beginning, development schedule may be delay due to communication error that cause by error calculation checksum. Using this software, you can get checksum value easily.
- ◆ **Duplicate PLC Service** - It provides program package concept. And you can read PLC internal important information (system auto setting) and save to a file (It is called program package, including program and all important system parameters) or copy to other PLC after finishing reading.
- ◆ **Special Instruction wizard** - provides settings of various special instructions, including PID control, high-speed I/O. User can finish program structure easily by filling table. For beginner, that is an easy and complete learning method. For programmer, that is easy method to set without miscellaneous setting of query and memory.

Variety number systems Interface

10.Variety number systems for monitor :

- ◆ 16/32 bits of binary number, decimal number and hexadecimal number Input/display with Integers and floating points
- ◆ ASCII, binary number, decimal number, hexadecimal number and BCD display



Summary of Basic Instructions

Instructions List

*Applicable models ES series below includes EX and SS series, EP includes SA series and SX series.

Instruction Code	Function	Ladder Diagram	Applicable model			Instruction Code	Function	Ladder Diagram	Applicable model			
			ES	EP	EH				ES	EP	EH	
Contact	LD	Load contact A		○	○	Coil	DCNT	32-bit counter		○	○	
	LDI	Load contact B		○	○		PLS	Rising-edge output		○	○	
	LDP	Rising-edge detection operation starts		○	○		PLF	Falling-edge output		○	○	
	LDF	Falling-edge detection operation starts		○	○		MC	Connect the common series connection contacts		○	○	
	AND	Series connection with A contact		○	○		MCR	Disconnect the common series connection contacts		○	○	
	ANI	Series connection with B contact		○	○		P	Pointer	P0-P255	○	○	
	ANDP	Rising-edge detection series connection		○	○		I	Interrupt pointer	I□□□	○	○	
	ANDF	Falling-edge detection series connection		○	○		MPS	Save the operation result		○	○	
	OR	Parallel connection with A contact		○	○		MRD	Read the operation result (the pointer not moving)		○	○	
	ORI	Parallel connection with B contact		○	○		MPP	Read the result		○	○	
	ORP	Rising-edge detection parallel connection		○	○		INV	Inverting operation		○	○	
	ORF	Falling-edge detection parallel connection		○	○		NOP	No function	In IL mode, cover deleted program by NOP instruction to reserve program capacity.	○	○	
	ANB	Series connects the circuit block		○	○		END	Program end		○	○	
	ORB	Parallel connects the circuit block		○	○		Step ladder instruction STL / RET Sequential control can be divided into several Steps or phases and there is action for each step. There is general transition to transfer to the next step. Once it goes to next step, next step's action will start and the previous step will be cleared. This is called sequential function chart (SFC). STL/RET are provided for SFC algorithm. Refer to Delta PLC application manual (programming) for detail.			○	○	
	Coil	OUT	Drive coil		○		○	STL	Step transition ladder start instruction		○	○
		SET	Action latched (ON)		○		○	RET	Step transition ladder return instruction		○	○
RST		Clear the contacts or the registers		○	○				○	○		
TMR		16-bit timer		○	○				○	○		
	CNT	16-bit counter		○	○				○	○		

Summary of Application Instructions

Instructions List

*Applicable models ES series below includes EX and SS series, EP includes SA series and SX series

Classification	API	Mnemonic Codes	Instruction	Instruction	Function	Applicable models			Classification	API	Mnemonic Codes	Instruction	Instruction	Function	Applicable models		
						ES	EP	EH							ES	EP	EH
Loop Control	00	CJ	-	○	Conditional Jump	○	○	○	Data Operation	37	WSFL	-	○	Shift the register to the left	-	○	○
	01	CALL	-	○	Call subroutine	○	○	○		38	SFWR	-	○	Shift register write	-	○	○
	02	SRET	-	-	Subroutine return	○	○	○		39	SFRD	-	○	Shift register read	-	○	○
	03	IRET	-	-	Interrupt return	○	○	○		40	ZRST	-	○	Resets a range of device specified	○	○	○
	04	EI	-	-	Enable interrupts	○	○	○		41	DECO	-	○	8 → 256 bits decoder	○	○	○
	05	DI	-	-	Disable interrupts	○	○	○		42	ENCO	-	○	256 → 8 bits encoder	○	○	○
	06	FEND	-	-	First end	○	○	○		43	SUM	○	○	Sum of ON bits	○	○	○
	07	WDT	-	○	Watchdog timer refresh	○	○	○		44	BON	○	○	Check specified bit status	○	○	○
	08	FOR	-	-	Start of FOR-NEXT loop	○	○	○		45	MEAN	○	○	Mean value	○	○	○
Transmission/Comparison	09	NEXT	-	-	End of FOR-NEXT loop	○	○	○	46	ANS	-	-	Alarm device output	-	○	○	
	10	CMP	○	○	Compare	○	○	○	47	ANR	-	○	Alarm device reset	-	○	○	
	11	ZCP	○	○	Zone compare	○	○	○	48	SQR	○	○	Square root of BIN	○	○	○	
	12	MOV	○	○	Data Move	○	○	○	49	FLT	○	○	Convert BIN integer to binary floating point	○	○	○	
	13	SMOV	-	○	Shift move	-	○	○	50	REF	-	○	I/O refresh	○	○	○	
	14	CML	○	○	Complement	○	○	○	51	REFF	-	○	Refresh and adjust the response time of input filter	-	○	○	
	15	BMOV	-	○	Block move	○	○	○	52	MTR	-	-	Input matrix	-	○	○	
	16	FMOV	○	○	Fill move	○	○	○	53	HSCS	○	-	High speed counter comparison SET	○	○	○	
	17	XCH	○	○	Data exchange	○	○	○	54	HSCR	○	-	High speed counter comparison RESET	○	○	○	
Four Fundamental Operations of Arithmetic	18	BCD	○	○	Convert BIN data into BCD	○	○	○	55	H6Z	○	-	Zone comparison (High-speed counter)	-	○	○	
	19	BIN	○	○	Convert BCD data into BIN	○	○	○	56	SPD	-	-	Speed detection	○	○	○	
	20	ADD	○	○	Perform the addition of BIN data	○	○	○	57	PLSY	○	-	Pulse output	○	○	○	
	21	SUB	○	○	Perform the subtraction of BIN data	○	○	○	58	PWM	-	-	Pulse width modulation output	○	○	○	
	22	MUL	○	○	Perform the multiplication of BIN data	○	○	○	59	PLSR	○	-	Pulse wave output with acceleration/deceleration speed	○	○	○	
	23	DIV	○	○	Perform the division of BIN data	○	○	○	60	IST	-	-	Manual/Auto control	○	○	○	
	24	INC	○	○	Perform the addition of 1	○	○	○	61	SER	○	○	Search a data stack	-	○	○	
	25	DEC	○	○	Perform the subtraction of 1	○	○	○	62	ABSD	○	-	Absolute drum sequencer	-	○	○	
	26	WAND	○	○	Perform the logical product (AND) operation	○	○	○	63	INCD	-	-	Increment drum sequencer	-	○	○	
Rotation and Displacement	27	WOR	○	○	Perform the logical sum (OR) operation	○	○	○	64	TTMR	-	-	Teaching timer	-	○	○	
	28	WXOR	○	○	Perform the exclusive logical add (XOR) operation	○	○	○	65	STMR	-	-	Special timer	-	○	○	
	29	NEG	○	○	Negation	○	○	○	66	ALT	-	○	On/Off alternate instruction	○	○	○	
	30	ROR	○	○	Rotate to the right	○	○	○	67	RAMP	-	-	Ramp signal	-	○	○	
	31	ROL	○	○	Rotate to the left	○	○	○	69	SORT	-	-	Data sort	-	○	○	
	32	RCR	○	○	Rotate to the right with the carry flag attached	○	○	○	External I/O Display	70	TKY	○	-	10-key keypad input	-	○	○
	33	RCL	○	○	Rotate to the left with the carry flag attached	○	○	○		71	HKY	○	-	16-key keypad input	-	○	○
	34	SFTR	-	○	Shift the data of device specified to the right	○	○	○		72	DSW	-	-	Digital Switch Input	-	○	○
	35	SFTL	-	○	Shift the data of device specified to the left	○	○	○		73	SEGD	-	○	Decode the 7-step display panel	○	○	○
36	WSFR	-	○	Shift the register to the right	-	○	○	74	SEGL	-	-	7-step display scan output	○	○	○		

Summary of Application Instructions

Instructions List

* Applicable models ES series below includes EX and SS series, EP includes SA series and SX series

Classification	API	Mnemonic Codes	D Instruction	P Instruction	Function	Applicable models			
						ES	EP	EH	
External I/O Display	75	ARWS	-	-	Arrow keypad input	-	○	○	
	76	ASC	-	-	ASCII code conversion	-	○	○	
	77	PR	-	-	Print	-	○	○	
	78	FROM	○	○	Read special module CR data	○	○	○	
	79	TO	○	○	Special module CR data write in	○	○	○	
	Serial I/O	80	RS	-	-	Serial data communication	○	○	○
		81	PRUN	○	○	Octal number system transmission	-	○	○
		82	ASCI	-	○	Convert HEX to ASCII	○	○	○
		83	HEX	-	○	Convert ASCII to HEX	○	○	○
		84	CCD	-	○	Check code	-	○	○
85		VRRD	-	○	Potentiometer read	-	○	○	
86		VRSC	-	○	Potentiometer scale	-	○	○	
87		ABS	○	○	Absolute value	○	○	○	
88		PID	○	-	PID calculation	○	○	○	
Basic Instructions		89	PLS	-	-	Rising-edge output	○	○	○
	90	LDP	-	-	Rising-edge detection operation	○	○	○	
	91	PDF	-	-	Falling-edge detection operation	○	○	○	
	92	ANDP	-	-	Series connection instruction for the rising-edge detection operation	○	○	○	
	93	ANDF	-	-	Series connection instruction for the falling-edge detection operation	○	○	○	
	94	ORP	-	-	Parallel connection instruction for the rising-edge detection operation	○	○	○	
	95	ORF	-	-	Parallel connection instruction for the falling-edge detection operation	○	○	○	
	96	TMR	-	-	Timer	○	○	○	
	97	CNT	○	-	Counter	○	○	○	
	98	INV	-	-	Inverting operation	○	○	○	
Communication Instruction of Delta AC Motor Drive	99	PLF	-	-	Falling-edge output	○	○	○	
	100	MODRD	-	-	MODBUS data Read	○	○	○	
	101	MODWR	-	-	MODBUS data write in	○	○	○	
	102	FWD	-	-	VFD-A series drive forward instruction	○	○	○	
	103	REV	-	-	VFD-A series drive reverse instruction	○	○	○	
	104	STOP	-	-	VFD-A series drive stop instruction	○	○	○	
	105	RDST	-	-	VFD-A series drive status read	○	○	○	
	106	RSTEF	-	-	VFD-A series drive abnormal reset	○	○	○	
	107	LRC	-	○	LRC error check	○	○	○	
	108	CRC	-	○	CRC error check	○	○	○	
Communication Instruction of Delta AC Motor Drive	109	SWRD	-	○	Digital switch read	-	○	○	
	110	ECMP	○	○	Binary floating point comparison	○	○	○	
	111	EZCP	○	○	Binary floating point zone comparison	○	○	○	
	Floating Operation	116	RAD	○	○	Degree Radian	-	○	○
		117	DEG	○	○	Radian Degree	-	○	○
		118	EBCD	○	○	Convert binary floating point to decimal floating point	○	○	○
		119	EBIN	○	○	Convert decimal floating point to binary floating point	○	○	○
		120	EADD	○	○	Binary floating point addition	○	○	○
		121	ESUB	○	○	Binary floating point subtraction	○	○	○
		122	EMUL	○	○	Binary floating point multiplication	○	○	○
123		EDIV	○	○	Binary floating point division	○	○	○	
124		EXP	○	○	Perform exponent operation of binary floating point	○	○	○	
125		LN	○	○	Perform natural logarithm operation of binary floating point	○	○	○	
Additional Instructions	126	LOG	○	○	Perform logarithm operation of binary floating point	○	○	○	
	127	ESQR	○	○	Square root of binary floating point	○	○	○	
	128	POW	○	○	Perform power operation of binary floating point	○	○	○	
	129	INT	○	○	Convert binary floating point to BIN integer	○	○	○	
	130	SIN	○	○	Sine operation of binary floating point	○	○	○	
	131	COS	○	○	Cosine operation of binary floating point	○	○	○	
	132	TAN	○	○	Tangent operation of binary floating point	○	○	○	
	133	ASIN	○	○	Arcsine operation of binary floating point	-	○	○	
	134	ACOS	○	○	Arccosine operation of binary floating point	-	○	○	
	135	ATAN	○	○	Arctangent operation of binary floating point	-	○	○	
Position Control	136	SINH	○	○	Hyperbolic sine operation of binary floating point	-	○	○	
	137	COSH	○	○	Hyperbolic cosine operation of binary floating point	-	○	○	
	138	TANH	○	○	Hyperbolic tangent operation of binary floating point	-	○	○	
	143	DELAY	-	○	Delay instruction	-	○	○	
	144	GPWM	-	-	General pulse width modulation output	-	○	○	
	146	FTC	-	-	Fuzzy temperature control	-	○	○	
	147	SWAP	○	○	Swap high/low byte	○	○	○	
	148	MEMR	○	○	Data backup MEMORY read	-	○	○	
	149	MEMW	○	○	Data backup MEMORY write in	-	○	○	
	150	MODRW	-	-	MODBUS data read/write in	○	○	○	
Position Control	151	PWD	-	-	Input pulse width detection	-	○	○	
	152	RTMU	-	-	Start to measure the execution time of I interrupt	-	○	○	
	153	RTMD	-	-	End to measure the execution time of I interrupt	-	○	○	
	154	RAND	-	○	Random value	-	○	○	
	155	ABSR	○	-	ABS current value read	-	○	○	
	156	ZRN	○	-	Zero point return	-	○	○	
	157	PLBY	○	-	Variable speed pulse output	-	○	○	

Summary of Application Instructions

Instructions List

* Applicable models ES series below includes EX and SS series, EP includes SA series and SX series

Classification	API	Mnemonic Codes	D Instruction	P Instruction	Function	Applicable models			
						ES	EP	EH	
Positioning Control	158	DRVI	○	-	Drive to increment	-	○	○	
	159	DRVA	○	-	Drive to absolute	-	○	○	
	Perpetual Calendar	160	TCMP	-	○	Time compare	-	○	○
		161	TZCP	-	○	Time zone compare	-	○	○
		162	TADD	-	○	Time addition	-	○	○
		163	TSUB	-	○	Time subtraction	-	○	○
		166	TRD	-	○	Time data read	-	○	○
		167	TWR	-	○	Time data write in	-	○	○
		169	HOUR	○	-	Hour meter	-	○	○
		Gray Code	170	GRY	○	○	Convert BIN to Gray code	-	○
171			GBIN	○	○	Convert Gray code to BIN	-	○	○
Matrix Handling			180	MAND	-	○	Matrix AND	-	○
	181		MOR	-	○	Matrix OR	-	○	○
	182		MXOR	-	○	Matrix XOR	-	○	○
	183		MXNR	-	○	Matrix NOR	-	○	○
	184		MINV	-	○	Matrix inverse	-	○	○
	185		MCMP	-	○	Matrix compare	-	○	○
	186		MBRD	-	○	Matrix bit read	-	○	○
	187		MBWR	-	○	Matrix bit write	-	○	○
	188	MBS	-	○	Matrix bit shift	-	○	○	
	189	MBR	-	○	Matrix bit rotate	-	○	○	
Contact Type Logic Operation	190	MBC	-	○	Matrix bit state count	-	○	○	
	198	HST	-	○	High speed counter	-	○	○	
	215	LD&	○	-	Comparison contact is ON when S1 & S2 is true	-	○	○	
	216	LD	○	-	Comparison contact is ON when S1 S2 is true	-	○	○	
	217	LD^	○	-	Comparison contact is ON when S1 ^ S2 is true	-	○	○	
	218	AND&	○	-	Comparison contact is ON when S1 & S2 is true	-	○	○	
	219	AND	○	-	Comparison contact is ON when S1 S2 is true	-	○	○	
	220	AND^	○	-	Comparison contact is ON when S1 ^ S2 is true	-	○	○	
	221	OR&	○	-	Comparison contact is ON when S1 & S2 is true	-	○	○	
	222	OR	○	-	Comparison contact is ON when S1 S2 is true	-	○	○	
Contact Type Logic Operation	223	OR^	○	-	Comparison contact is ON when S1 ^ S2 is true	-	○	○	
	224	LD=	○	-	Comparison contact is ON when S1 = S2 is true	○	○	○	
	225	LD>	○	-	Comparison contact is ON when S1 > S2 is true	○	○	○	
	226	LD<	○	-	Comparison contact is ON when S1 < S2 is true	○	○	○	
	228	LD<>	○	-	Comparison contact is ON when S1 ≠ S2 is true	○	○	○	
	229	LD≤	○	-	Comparison contact is ON when S1 ≤ S2 is true	○	○	○	

◆ Applicable models ES series above includes EX and SS series; EP includes SA/SX series.

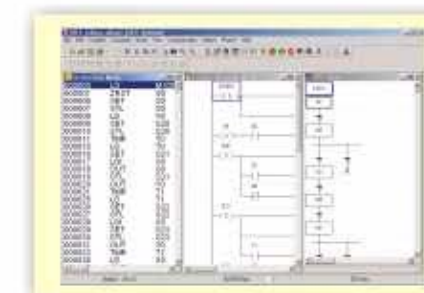
◆ Above instruction for ES/EX/SS models don't possess pulse execution instruction (P instruction).

◆ Refer to DVP-PLC application manual for complete instruction.

* Please contact distributor for purchasing

◆ Please contact your distributor for free WPLSoft (DVP-PLC programming software tool).

◆ There are three languages (IL, LAD and SFC) for input and they can convert to another. It is windows based for user to use and learn easily. It also provides PLC program package to copy PLC rapidly.



<p>● MPU</p> <p>1. Total points (output/input) 2. Model series ES : ES MPU EX : EX MPU SS : SS MPU SA : SA MPU SX : SX MPU EP : EP MPU EH : EH MPU 3. Input power 00 : AC power input 01 : DC power input (L Type) 11 : DC power input (H Type) 4. Output type R : Relay T : Transistor 5. Upgrade version code (only for ES/EX/SS MPU) 2: Upgrade version for ES/EX/SS MPU</p>	<p>● DI/DO Extension Unit</p> <p>1. Total points (output/input) 2. Applicable model X : for ES/EX MPU S : for SS/SX/SA MPU P : for EP MPU H : for EH MPU 3. I/O type M : Input point N : output point P : I/O mix 4. Input power 00 : AC power input 01 : DC power input (L Type) 11 : DC power input (H Type) 5. Output type R : Relay T : Transistor ※ There are two types (L-Type and H-Type) in DC input type sorted by shape for ES/EX series. Refer to page 35 for detail.</p>	<p>● AI/AO Extension Unit</p> <p>1. Total points (output/input) 2. Extension type AD : analog/digital conversion module DA : digital/analog conversion module PT : temperature module - PT100 type TC : temperature module - thermocouple RT : temperature module resistor thermocouple XA : AD and DA function 3. Applicable model S : for SS/SA/SX MPU P : for EP MPU H : for EH MPU</p>
<p>● PI/PO Extension Unit</p> <p>1. Total number of output/input channels 2. Extension type HC : high-speed counter module PU : single-axis positioning module 3. Applicable model H : for EH MPU</p>	<p>● NI/NO Extension Unit</p> <p>1. Number 2. Extension type BD : BCD DIP switch module KY : matrix keypad module 3. Applicable model H : for EH MPU</p>	<p>● Peripheral Equipment</p> <p>1. Equipment name HPP : Handheld programming panel DU : digital setup display 2. Type/function 01: Type 01 02: Type 02</p>
<p>● Accessory cable</p> <p>1. Accessories 2. Type CAB: Cable Connected type 1, 2, 3, 4, ... 4. Length 15 : 1.5m 30 : 3.0m</p>	<p>● Accessory-others</p> <p>1. Accessories 2. Type BT: Battery 3. Battery type 01, 02 ...</p>	<p>● Function Card</p> <p>1. Function card 2. Type 232 : RS-232 card 422 : RS-422 card 2OT : 2DO card, transistor output... 3. connected function (special definition by function card) S: Slave model (only for COM3)</p>

ES Standard MPU												
Spec. Model	Power	Input / output Specification						Dimension				
		Input Unit			Output Unit							
		Point	Type	Point	Type							
DVP14ES00R2	100~240VAC +10% -15%	8	DC24V/5mA Sink or Source	6	Relay AC250V/DC30V 2A/1point	Fig. 1						
DVP14ES00T2		8		6		Fig. 2						
DVP24ES00R2		16		8								
DVP24ES00T2		16		8								
DVP32ES00R2		16		16		transistor DC5~30V 0.3A/1point@40°C	Fig. 3					
DVP32ES00T2		16		16								
DVP80ES00R2		36		24								
DVP80ES00T2		36		24								
EX Special Function MPU												
Spec. Model		Power		Input / output Specification						Dimension		
	Input Unit			Output Unit								
	Point		Type	Point	Type							
DVP20EX00R2	100~240VAC +10% -15%	8	4	DC24V/5mA Sink or Source	-20~-20mA or -10~+10V	6	2	Relay Transistor 0~20mA or 0~10V	Fig. 2			
DVP20EX00T2		8	4		6	2						
DVP20EX11R2		DC24V	8		4	6	2					
Digital I/O Extension Unit for ES/EX Series												
Spec. Model	Power	Input / output Specification						Dimension				
		Input Unit			Output Unit							
		Point	Type	Point	Type							
DVP08XM11N	DC24V +20% -15%	8	DC24V/5mA Sink or Source	0	None	Fig. 4						
DVP16XM11N		16		0		Fig. 1						
DVP08XN11R		0		8			Fig. 4					
DVP08XN11T		0		8								
DVP16XN11R		0		16		relay AC250V/DC30V 2A/1Point	Fig. 2					
DVP16XN11T		0		16								
DVP24XN11R		0		24								
DVP24XN11T		0		24								
DVP08XP11R		4		4	transistor DC5~30V 0.3A/1point@40°C			Fig. 4				
DVP08XP11T		4		4								
DVP24XP11R		16		8	Fig. 2							
DVP24XP11T		16		8								
DVP32XP11R		16		16								
DVP32XP11T		16		16								

*Refer to page 35 for dimension of ES/EX series MPU/extension unit.

Digital I/O Extension Unit for ES/EX Series

Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Point	Type	Point	Type	
DVP24XN00R	100~240VAC +10% -15%	0	DC24V/5mA Sink or Source	24	relay AC250V/DC30V 2A/1point	Fig. 2
DVP24XN00T		0		24		
DVP24XP00R		16		8	transistor DC5~30V	
DVP32XP00R		16		16	0.3A/1point@40°C	
DVP32XP00T		16		16		
DVP32XP01T		16		16		

ES Standard MPU (L Type)

Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Point	Type	Point	Type	
DVP14ES01R2	DC24V +20% -15%	8	DC24V/5mA Sink or Source	8	Relay AC250V/DC30V 2A/1point	Fig. 5
DVP14ES01T2		8		6		
DVP24ES01R2		16		8		
DVP24ES01T2		16		8	transistor DC5~30V	Fig. 6
DVP32ES01R2		16		16	0.3A/1point@40°C	
DVP32ES01T2		16		16		

Digital I/O Extension Unit for ES/EX Series (L Type)

Spec. Model	Input / output Specification					Dimension	
	Power	Input Unit		Output Unit			
		Point	Type	Point	Type		
DVP16XM01N	DC24V +20% -15%	16	DC24V/5mA Sink or Source	0	None	Fig. 5	
DVP16XN01R		0		16	Relay AC250V/DC30V 2A/1point		
DVP16XN01T		0		16			
DVP24XN01R		0		24		transistor DC5~30V	
DVP24XN01T		0		24			0.3A/1point@40°C
DVP24XP01R		16		8			
DVP24XP01T		16		8			
DVP32XP01R		16		16			
DVP32XP01T		16		16			

SS Standard MPU (module type)

Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Point(DI)	Type	Point(DO)	Type	
DVP14SS11R2	DC24V +20% -15%	8	DC24V/5mA Sink or Source	6	Relay	Refer to P36
DVP14SS11T2		8		6	Transistor	

Digital I/O Extension Unit for SS/SA/SX Series

Spec. Model	Input / output Specification					Dimension	
	Power	Input Unit		Output Unit			
		Point	Type	Point	Type		
DVP08SM11N	DC24V +20% -15%	8	DC24V/5mA Sink or Source	0	None	Refer to P36	
DVP08SN11R		0		8	relay AC250V/DC30V 1.5A/1Point		
DVP08SN11T		0		8			
DVP08SP11R		4		4			transistor DC5~30V 0.3A/1Point@40°C
DVP08SP11T		4		4			
DVP16SP11R		8		8			
DVP16SP11T		8		8			

Analog I/O Extension Module for SS/SA/SX Series

Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Channel number	Explanation	Channel number	Explanation	
DVP04AD-S	DC24V +20% -15%	4	±10V or ±20 mA / 14bits	0	—	Refer to P38
DVP04DA-S		0	—	4	0~10V or 0~20 mA / 12bits	
DVP02DA-S		0	—	2	0~10V or 0~20 mA / 12bits	
DVP06XA-S		4	±10V or ±20 mA / 12bits	2	0~10V or 0~20 mA / 12bits	
DVP04PT-S		4	-200°C~600°C / 14 bits(0.1°C)	0	—	
DVP04TC-S		4	-100°C~1000°C / 14 bits(0.1°C)	0	—	
DVP08RT-S		8	-20°C~150°C / 12 bits(0.1°C)	0	—	

Power Output Module

Spec. Model	Input / output Specification			Dimension
	Input Unit	Output Unit		
DVPPS01	100~240VAC, -15%~+10%, surge voltage can be to 320VAC	Output voltage : 24VDC, max. Is : 1A	Refer to P38	
DVPPS02	100~240VAC, -15%~+10%, surge voltage can be to 320VAC	Output voltage : 24VDC, max. Is : 2A		

EH Standard MPU

Spec. Model	Input / output Specification					Dimension	
	Power	Input Unit		Output Unit			
		Point	Type	Point	Type		
DVP16EH00R	100~240VAC +10% -15%	8	DC24V/5mA Sink or Source	8	Relay AC250V/DC30V 2A/1Point	Refer to P37	
DVP16EH00T		8		8			
DVP20EH00R		12		8			transistor DC5~30V
DVP20EH00T		12		8			
DVP32EH00R		16		16			
DVP32EH00T		16		16			
DVP48EH00R		24		24			
DVP48EH00T		24		24			

EH Standard MPU

Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Point	Type	Point	Type	
DVP64EH00R	100~240VAC +10% -15%	32	DC24V/5mA Sink or Source	32	Relay	Refer to P37
DVP64EH00T		32		transistor		
DVP80EH00R		40		Relay		
DVP80EH00T		40		transistor		

Note: For DVP20EH00T and DVP32EH00T, there are high-speed pulse output points Y0 and Y2.

EH Digital I/O Extension Unit

Spec. Model	Input / output Specification					Dimension		
	Power	Input Unit		Output Unit				
		Point	Type	Point	Type			
DVP08HM11N	DC24V +20% -15%	8	DC24V/5mA Sink or Source	0	None	Refer to P37		
DVP16HM11N		16		0				
DVP08HN11R		0		relay AC250V/DC30V 2A/1Point	8			
DVP08HN11T		0			8			
DVP08HP11R		4			4			
DVP08HP11T		4			4			
DVP32HP00R		100~240VAC -15%~+10%		16	transistor DC5~30V 0.3A/1Point@40°C		16	
DVP32HP00T				16			16	
DVP48HP00R				24			24	
DVP48HP00T				24			24	

EH analog I/O Extension Unit

Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Channel number	Explanation	Channel number	Explanation	
DVP04AD-H	DC24V +20% -15%	4	±10V or ±20 mA / 14bits	0	—	Refer to P37
DVP04DA-H		0	—	4	0~10V or 0~20 mA / 12bits	
DVP04PT-H		4	-200°C~600°C / 14 bits(0.1°C)	0	—	
DVP04TC-H		4	-100°C~1000°C / 14 bits(0.1°C)	0	—	
DVP06XA-H		4	±10V or ±20 mA / 12bits	2	0~10V or 0~20 mA / 12bits	

EH Special Extension Unit

Spec. Model	Input / output Specification			Dimension
	Power	Input Unit		
		Output Unit		
DVP01PU-H	DC24V +20% -15%	—	200KHz /Line output/1CH	Refer to P37
DVP01HC-H		200KHz, +5V/+12V/+24 V Input level/1CH	—	
DVP02HC-H		200KHz, +24V Input level/2CH	—	
DVP08BD-H	DC24V (supply from MPU)	8-bit DIP Switch module		Refer to P37
DVP08KY-H		Matrix keypad Input module(max. 1s 8*8)		

SA Standard MPU

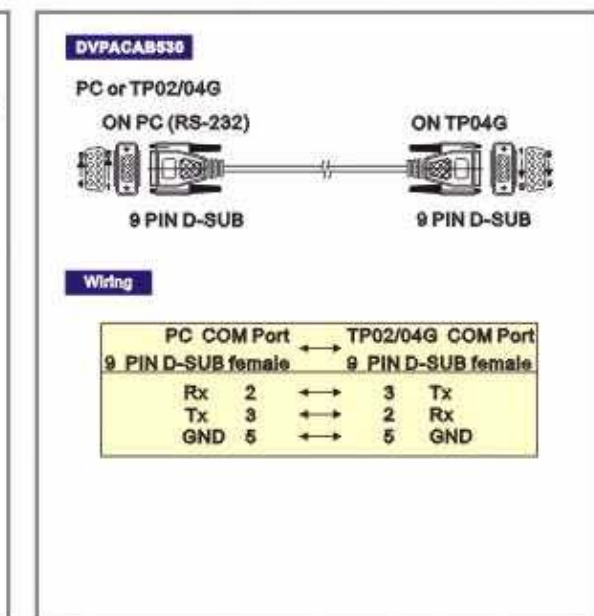
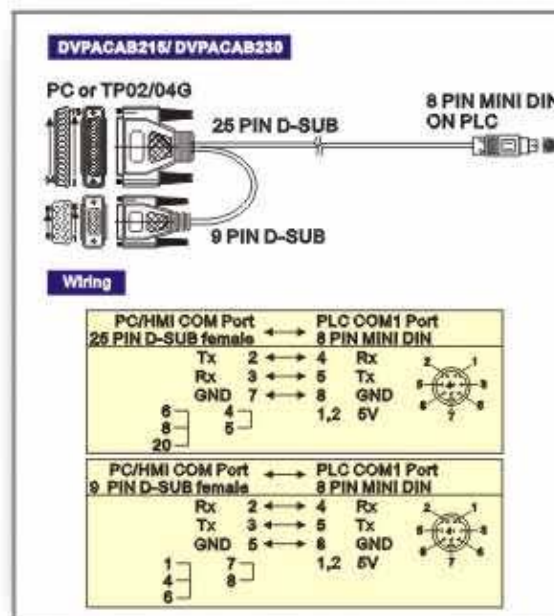
Spec. Model	Input / output Specification					Dimension
	Power	Input Unit		Output Unit		
		Point	Type	Point	Type	
DVP12SA11R	DC24V +20% -15%	8	DC24V/5mA Sink or Source	4	Relay	Refer to P36
DVP12SA11T		8		4	transistor	

SX Special Function MPU





Spec. Model	Input / output Specification								Dimension	
	Power	Input Unit				Output Unit				
		Point	DI	AI	Type	Point	DO	AO		Type
DVP10SX11R	DC24V +20% -15%	4	2	DC24V/5mA Sink or Source	-20~20mA or -10~+10V	2	2	Relay	-20~20mA or -10~+10V	Refer to P36
DVP10SX11T		4	2			2	2	transistor		

Accessories

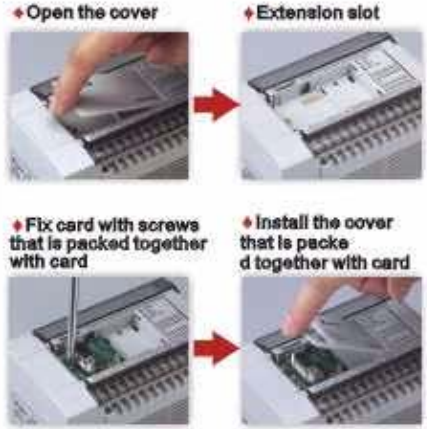
Model number	Type	Function	Remark
DVPACAB115	cable	HPP02⇔PLC / 1.5m	This cable is packaged with DVPHPP02
DVPACAB215	cable	PC(9 PIN & 25 PIN D-SUB) ⇔PLC / 1.5m	Could be connector for PLC to connect TP series or other HMI
DVPACAB2A30	cable	PC(9 PIN D-SUB) ⇔PLC / 3m	User also can use following wiring to make cable with suitable length
DVPACAB230	cable	PC(9 PIN & 25 PIN D-SUB) ⇔PLC / 3m	
DVPACAB315	cable	HPP02⇔PC / 1.5m	Use when HPP02 connects to PC
DVPACAB403	cable	I/O signal extension line · 30cm	MPU⇔extension unit or extension unit extension unit (for ES/EX series)
DVPACAB530	cable	TP02/04G⇔PC/ 3m	TP02/04G program planning
DVPABT01	battery	3.6V LI battery	For EH/EP/SA/SX MPU
DVPABT02	battery	3.6V LI battery	For TP04G



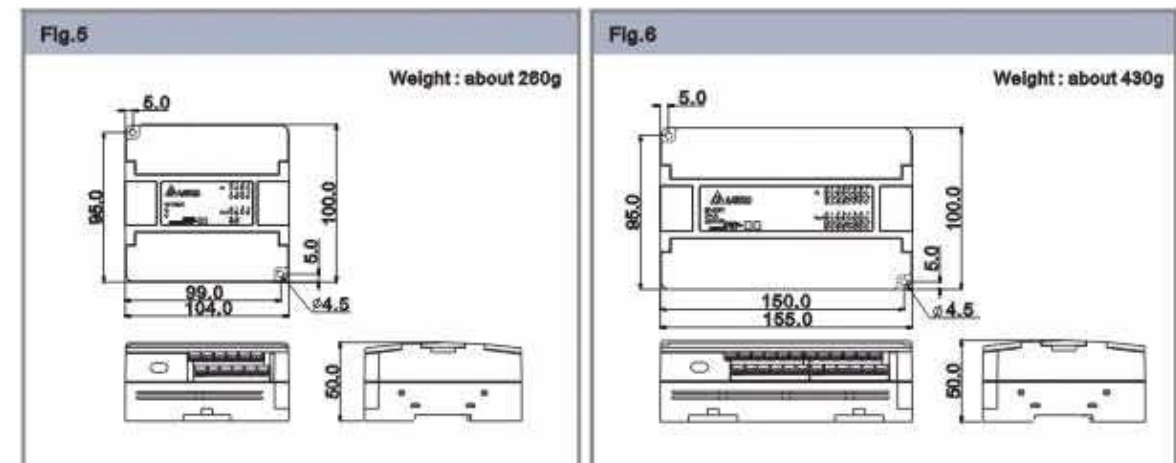
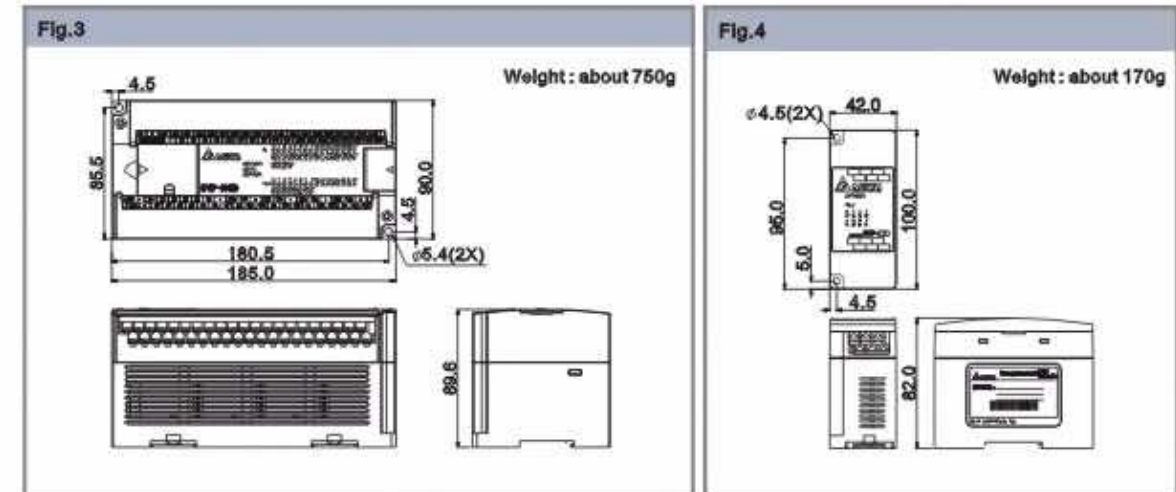
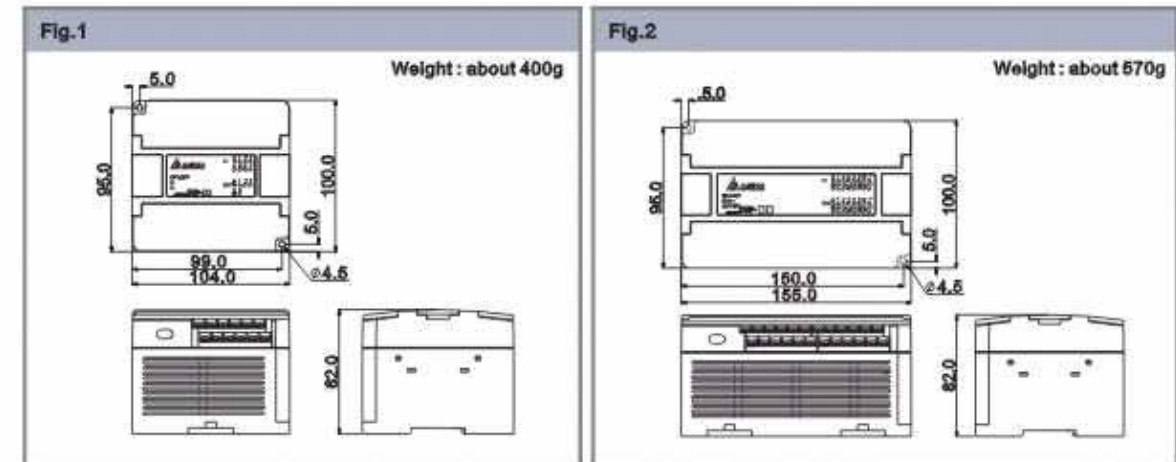
Peripheral Equipment

Model no.	Equipment	Function
 DVPHPP02	Handheld programming panel	1.Supports program read/write and editor for all DVP-PLC series 2.Monitor and set all PLC internal devices 3.Built-in retentive memory. Once it connects to MPU more than 5 minutes, internal program will maintain for 3-7 days. 4.Built-in data backup memory card. It can save data permanently and also exchange data with EH MPU.
 DVPDU01	Digital setup display	1.Embedded design: Could insert into extension slot of EH MPU (32 points and more). 2.Connect to RS-232 (COM1) of all DVP-PLC series MPU with accessory cable. 3.Monitor and set PLC device; copy program (for all series)
 TP04G-AS2	Operation interface panel series	1.Resolution is 128*64 and max. is 8*4 Chinese characters, also support multilanguage 2.Built-in two communication ports (RS-232 and RS-485 can be used simultaneously) 3.Built-in real clock time and communication/alarm LED indication 4.Allow to external program copy, copy program rapidly, save download time 5.Built-in variety object shape
 TP02G-AS1	Operation interface panel series	1.Resolution is 160*32 and max. is 10*2 Chinese characters, also support multilanguage 2.Built-in two communication ports (RS-232 and RS-485 can be used simultaneously) 3.Allow to external program copy, copy program rapidly, save download time 4.Built-in variety object shape and communication/alarm LED indication
 TP-PCC	Program copy card	For TP series, copy program rapidly and save download time
WPLSoft	DVP-PLC program editor software, supports multilanguage (traditional Chinese, simplified Chinese and English)	
TPedit	Program editor software for TP series, supports Multilanguage (traditional Chinese, simplified Chinese and English)	

Extension card and data backup memory card (Only for EH MPU)

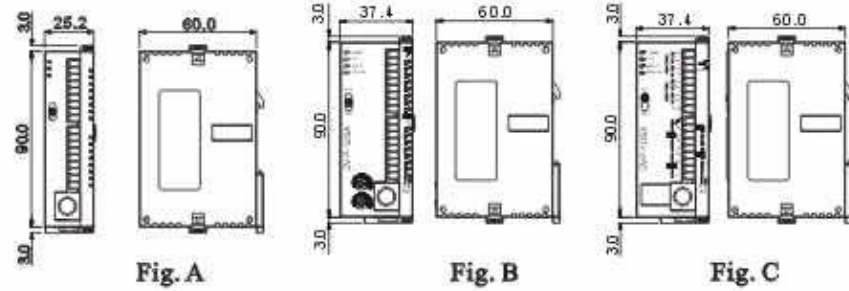
Model no.	Function	Connector	Installation
DVP-F232	Modify COM2 to RS-232	DB9 male	
DVP-F422	Modify COM2 to RS-422	5 PIN G type terminal	
DVP-F8ID	8-Input DIP switch (binary input)	-	
DVP-F4IP	Additional 4-digital input points (with photocoupler isolation)	5 PIN G type terminal	
DVP-F6VR	Additional 6-point Input potentiometer value	-	
DVP-F2AD	Additional analog inputs (2 points, resolution 12-bit)	5 PIN G type terminal	
DVP-F2DA	Additional analog outputs (2 points, resolution 12-bit)	5 PIN G type terminal	
DVP-F485S	Additional COM port (COM3), type: RS-485	5 PIN G type terminal	
DVP-F232S	Additional COM port (COM3), type: RS-232	DB9 female	
DVP-F2OT	Additional 2-digital output points (output type: transistor)	5 PIN G type terminal	
DVP-256FM	Data backup memory card	-	

ES/EX MPU/Extension Unit (Refer to P.29 for model number)



• Install with/without 35mm DIN rail
• Besides fig. 3, they are all fixed terminal. Fig. 3 is removal terminal for DVP60E800R2/T2.

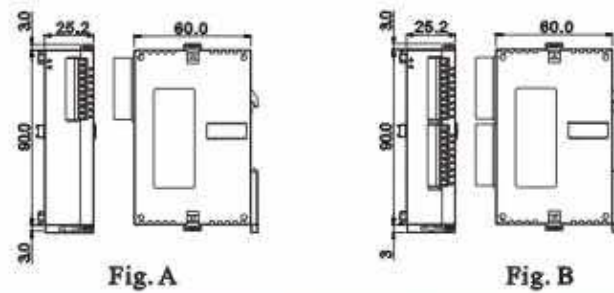
SS/SA/SX Series MPU



Model number	Fig.	Weight (g)
DVP148S11R2	A	104
DVP148S11T2	A	98
DVP128A11R	B	140
DVP128A11T	B	130
DVP108X11R	C	138
DVP108X11T	C	133

- 35mm DIN rail for fixed installation
- Removal terminal

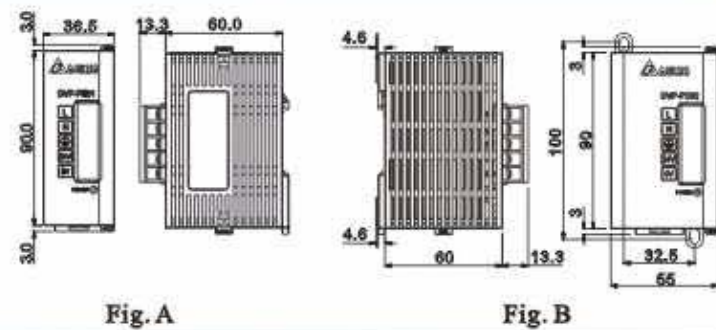
SS/SA/SX series -- DI/DO and Special Extension Module



Model number	Fig.	Weight (g)
DVP088M11N	A	84
DVP088N11R/T	A	88 / 88
DVP088P11R/T	B	80 / 70
DVP168P11R/T	B	96 / 76
DVP04AD-S	B	98
DVP04DA-S	B	98
DVP02DA-S	B	90
DVP06XA-S	B	88
DVP04PT-S	B	98
DVP08RT-S	B	88
DVP04TC-S	B	98

- 35mm DIN rail for fixed installation
- Removal terminal

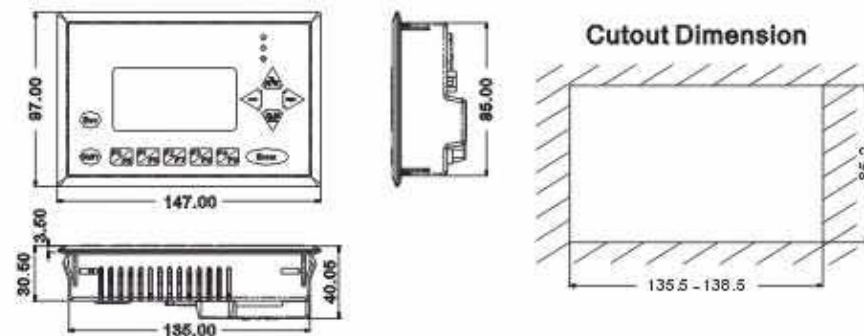
Power Output Module



Model number	Fig.	Weight (g)
DVPPS01	A	188
DVPPS02	B	250

- 35mm DIN rail for fixed installation
- Removal terminal (with cover)
- There is fixed installation hole for DVPPS02

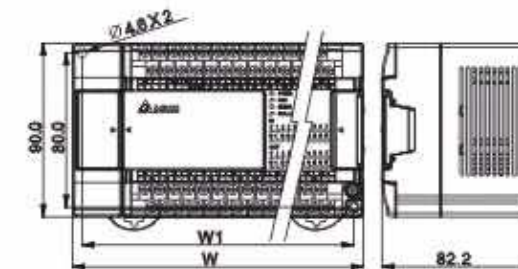
TP02G/TP04G Operation Interface Panels Series



Model number	Weight (g)
TP02G-AS1	284
TP04G	282

- Removal terminal

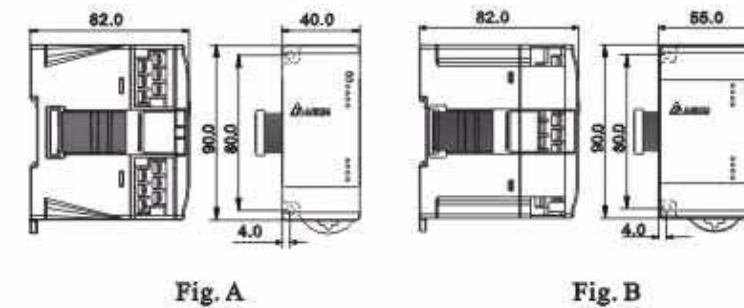
EH Series MPU



Model number	W(mm)	W1(mm)	Weight (g)
DVP16EH00R/T	113	103	500 / 480
DVP20EH00R/T	113	103	820 / 800
DVP32EH00R/T	143.5	133.5	862 / 812
DVP48EH00R/T	174	164	748 / 688
DVP64EH00R/T	212	202	836 / 756
DVP80EH00R/T	276	266	948 / 848

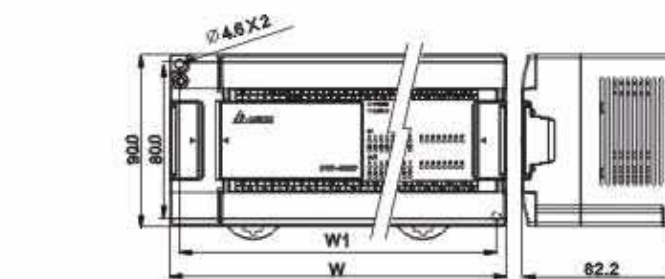
- Install with/without 35mm DIN rail
- Removal terminal

EH Series -- DI/DO and NI/NO Extension Module



Model number	Fig.	Weight (g)
DVP08HM11N	A	124
DVP16HM11N	B	160
DVP08HN11R/T	A	130 / 120
DVP08HP11R/T	A	138 / 118
DVP08KY-H	A	98
DVP08SD-H	A	100

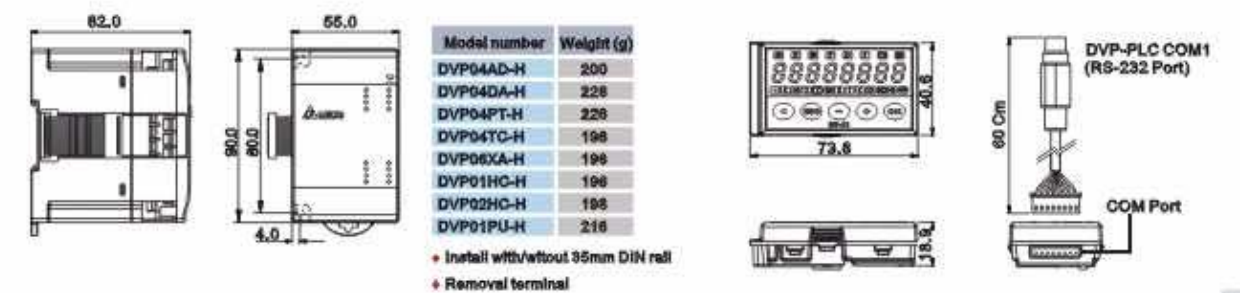
- Install with/without 35mm DIN rail
- Fixed terminal
- DVP16HM11N: removal terminal



Model number	W(mm)	W1(mm)	Weight (g)
DVP32HP00R/T	143.5	133.5	498 / 398
DVP48HP00R/T	174	164	616 / 576

- Install with/without 35mm DIN rail
- Removal terminal

EH Series Special Extension Module and Digital Display (DVPDU01)



Model number	Weight (g)
DVP04AD-H	200
DVP04DA-H	226
DVP04PT-H	226
DVP04TC-H	198
DVP06XA-H	198
DVP01HC-H	198
DVP02HC-H	198
DVP01PU-H	216

- Install with/without 35mm DIN rail
- Removal terminal